

Stas Minsker

Intro

machine learning is the study of algorithms that can learn from data, gradually improving their performance. *large datasets*

mathematical statistics (ST) is the science of making decision in the face of **uncertainty**.

small datasets

$$[Ex] \quad Y = \underset{\downarrow}{\alpha} + \beta_1 [interesting] + \beta_2 [genre] + \beta_3 [Budget] + \dots + \epsilon$$

\downarrow average rating (or?)

rating of a movie

$\in [0, 100]$

Netflix: wants to predict rating of a movie - ML

Disney: wants to make a movie with high rating - ST

needs to understand whether the model is statistically significant (hypothesis testing, etc. ...)

[Ex] Handwritten digits recognition - ml

ml	{	unsupervised learning	"raw data", no label	clustering, learning representation
		supervised learning	labeled	classification, prediction
		reinforcement learning	"multi-armed bandit problem"	exploration v.s. exploitation

Realizable case:

Binary classification $(X, Y) = (\text{instance}, \text{label})$
(observation, label)

[Ex] x - image, $Y \in \{+1, -1\}$ (eg: "cat", "dog")

$x \in S$ - set of all possible instances

statistical learning: we will assume that (X, Y) is random, in other words, it has a probability distribution P so we use language of probability theory

Supervised Learning:

$(X, Y) \in S \times \{+1, -1\}$

P is the distribution of (X, Y)

i.e. $P(A) = \text{Probability}((X, Y) \in A)$

Π is the distribution of X

Imposing the probabilistic model on (X, Y) takes us into realm of Statistical Learning Theory

Goal: predict label Y based on the observation x

The prediction rule is a function $g: S \rightarrow \{-1, +1\}$

The quality of a prediction rule g is measured by the classification / generalization error

$$L(g) = \text{Prob}(Y \neq g(X)) \quad (\text{one prediction})$$

The training data is a sequence $(X_1, Y_1), (X_2, Y_2), \dots, (X_n, Y_n)$ of i.i.d. pairs with distribution P .

An algorithm takes training data as an input and outputs $\hat{g}_n = \hat{g}_n((X_1, Y_1), \dots, (X_n, Y_n))$ a prediction rule

In general, we will consider 2 scenarios:

1) "Realizable" learning: there exists $g \in G$ s.t. $Y = g^*(X)$ with probability 1.

2) "Agnostic" learning: there is no $g \in G$ s.t. $Y = g^*(X)$ with probability 1.

Realizable scenario:

assume that the set G of all possible classification rules is finite.

By assumption, $\exists g^* \in G : Y = g^*(X)$ with prob 1

The Empirical Risk Minimization principle:

(training data) pick any \hat{g}_n that agrees with the training data ($\hat{g}_n(X_i) = Y_i, i=1, \dots, n$)

Question: what is $L(\hat{g}_n)$?

what is $\text{prob}(L(\hat{g}_n) > \epsilon) \leq ?$, given $\epsilon > 0$

Here, $L(g) = \text{Prob}(Y \neq g(X))$

let $G_B =$ "bad" classification rules $= \{g \in G : L(g) > \epsilon\}$

$\text{prob}(L(\hat{g}_n) > \epsilon) = \text{prob}(\hat{g}_n \in G_B)$

Takes $g \in G_B$, if $\hat{g}_n = g$, $g(X_i) \neq Y_i, i=1, 2, \dots, n$

$\text{prob}(g(X_i) \neq Y_i) > \epsilon$

$\text{prob}(g(X_i) = Y_i) \leq 1 - \epsilon$

$\Rightarrow \text{prob}(g(X_i) = Y_i, i=1, \dots, n) = P(g(X_1) = Y_1) \cdot P(g(X_2) = Y_2) \cdots P(g(X_n) = Y_n)$

$$= \prod_{i=1}^n P(g(X_i) = Y_i)$$

$$\leq (1 - \epsilon)^n$$

We show that $\forall g \in G_B, P(\hat{g}_n = g) \leq (1 - \epsilon)^n \leq e^{-\epsilon n}$

(since $1 - \epsilon \leq e^{-\epsilon}$)

Remainder: Union Bound: $P(A \cup B) \leq P(A) + P(B)$

\therefore If $G_B = \{g_1, \dots, g_k\}$, then $P(\hat{g}_n \in G_B) = P(\hat{g}_n = g_1 \text{ or } \hat{g}_n = g_2 \text{ or } \dots \text{ or } \hat{g}_n = g_k)$

$$\leq P(\hat{g}_n = g_1) + P(\hat{g}_n = g_2) + \dots + P(\hat{g}_n = g_k)$$

$$\leq k e^{-\epsilon n}$$

$$\leq |G| e^{-\epsilon n}$$

If one requires that $P(L(\hat{g}_n) \leq \epsilon) \geq 1 - \delta$

then $|G|e^{-\epsilon n} \leq \delta$

$$\Leftrightarrow n \geq \frac{\log \frac{|G|}{\delta}}{\epsilon}$$

E.g. if $G = 1024 = 2^{10}$, $\delta = 2^{-6}$, $\epsilon = 0.01$, what is n ? (最少有多少样本)

$$n \geq \frac{16 \log 2}{0.01} = 160 \log 2$$

Record some useful concepts:

ERM: pick a classifier that makes the smallest number of mistakes on observed data.

define: $L_n(g) = \frac{1}{n} \cdot \#\{1 \leq j \leq n : g(x_j) \neq y_j\}$

Remark: By Law of Large Number, $L_n(g) \xrightarrow{P} L(g)$ since $E(L_n(g)) = L(g)$

The ERM states that one pick \hat{g}_n that minimize $L_n(g)$ over $g \in G$

PAC: ("Probably Approximately Correct") learnability: Leslie Valiant '84

A class H of hypothesis / binary classifiers is PAC learnable:

if $\forall \epsilon, \delta \in (0, 1)$, any labeling function g^* , any distribution Π of X ,

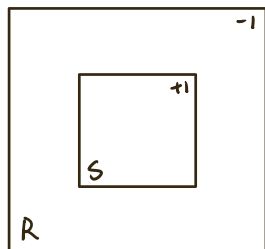
\exists algorithm A . (e.g. ERM) and a function $n = n(\epsilon, \delta, G)$ st. $\Pr(L(\hat{g}_n) > \epsilon) \leq \delta$

推论: Any finite set of binary classifiers is PAC-learnable

if we take $n \geq \frac{\log(|G|)}{\epsilon}$, we can satisfy $\Pr(L(\hat{g}_n) > \epsilon) \leq \delta$

Infinite set of classifiers

[Example A]



Area(R) = 2 (大方块)

Area(S) = 1

$$g^*(x) = \begin{cases} +1 & x \in S \\ -1 & x \in R \setminus S \end{cases}$$

let $G = \{\text{all binary function } g: R \rightarrow \{+1, -1\}\}$

Training Data: $(x_1, y_1), \dots, (x_n, y_n)$

$$\text{consider } \hat{g}_n(x) = \begin{cases} y_i, & x = x_i \text{ for } i=1, \dots, n \\ -1, & \text{else} \end{cases}$$

In particular, \hat{g}_n is consistent with ERM (sample 里见过的都对)

But $L(\hat{g}_n) = \Pr(Y \neq \hat{g}_n(x)) = \frac{1}{2} \rightarrow \text{overfitting}$

(assume that x is chosen uniformly from R) 选到点的概率是 0 \Rightarrow 几乎是 -1

$$x \sim U(0, 1) \quad \text{---} \frac{h}{x} \text{---}$$

$$\Pr(X=x) \leq \Pr(X \in [x-h, x+h]) \quad \forall h$$

since h can be as small as it wants to

$$\therefore \Pr(X=x) = 0$$

but all infinite G is not PAC learnable (?)

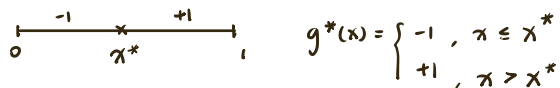
overfitting: $L(\hat{g}_n) \rightarrow 0$ (?)

if G is too "large", then any algorithm (in particular ERM) will produce a classifier with large misclassification error.

if G is "too large" \rightarrow it is not PAC learnable

An algorithm A is a map that takes G and $(x_i, y_i), i=1, \dots, n$ as input and outputs $\hat{g} \in G$.

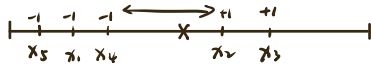
[Example B] $x \in [0, 1]$



$G = \{g_y, y \in [0, 1]\}$ \leftarrow 有定义解, 不是 all classifier, 但仍 infinite classifiers

$g_y(x) = \begin{cases} -1, & x \leq y \\ +1, & x > y \end{cases}$ } 只能分两段

$(x_1, y_1), \dots, (x_n, y_n)$ iid - training data



claim: G is PAC learnable (?)

\rightarrow To show this, we need to estimate its sample complexity

given $\epsilon, \delta > 0$, if $n \geq n(\epsilon, \delta)$, $\exists A$ such that, given a sample of size n ,

A outputs \hat{g} such that $L(\hat{g}) < \epsilon$ with prob $\geq 1 - \delta$

let's use ERM: specifically, let $\hat{x} = \max\{x_j : y_j = -1\}$

let $\hat{g}_n(x) = \begin{cases} -1, & x \leq \hat{x} \\ +1, & x > \hat{x} \end{cases}$

$\Pr(L(\hat{g}_n) > \epsilon) \leq (1 - \epsilon)^n$ (show this!)

[Example 1] Task: identify counterfeit banknotes

We know that real banknotes (a) color change under the light $\in [0, 1]$, with increment 0.1
 (b) red/blue fibers $\in [0, 100]$, with increment 1

realizable \leftarrow Assume that for every "real" banknote, (a)(b) belong to a specific range, vice versa

Assume that you have 100 banknotes, known to be real or not

\rightarrow X : banknote, Y : label {real/fake}

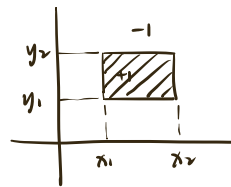
$X \in S$ Domain set = $\{(x, y) : x \in [0:0.1:1], y \in [0:1:100]\}$

Training data: 100 banknotes

Hypothesis class G : $g: S \rightarrow \{+1, -1\}$

$$g(x) = \begin{cases} +1, & x \in [x_1, x_2], y \in [y_1, y_2] \\ -1, & \text{else} \end{cases}$$

$$|G| \leq \binom{100}{2} \approx 2 \quad - \text{still manageable}$$



Assume that we want a classifier that makes at most 5% mistake.

What is the probability that you will get such a classifier from a sample size 100.

We proved that

$$\Pr(L(\hat{g}_{ERM}) > 0.05) \leq \frac{10^8}{2} (1-0.05)^{100}$$

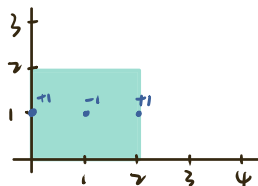
\rightarrow 1000 | G |
 $= \frac{10^8}{2} \cdot \frac{95^{100}}{10^{100}}$ prob 小于 1 万分之一 东西?

[Example 2] label (x_1, x_2) , $x_1, x_2 \in \mathbb{I}$, $0 \leq x_1 \leq 4$, $0 \leq x_2 \leq 3$

$G = \{ \text{rectangle with vertices } (x_1, x_2) \in [0, 4] \times [0, 3] \}$

Training set:

x_1	x_2	y
0	1	1
1	1	-1
2	1	1



let $g: [0, 4] \times [0, 3]$

$$L_n(g) = \frac{\#\{i \in n, Y \neq g(x_i)\}}{n} = \frac{1}{3} \leftarrow \text{empirical risk}$$

$(n=3)$

ERM: line segment $(0, 1)$ to $(2, 1)$

\rightarrow Agnostic learning (no perfect classifier)

"No Free Lunch" theorem

An algorithm A is a mapping from training data $(x_i, y_i)_{i=1}^n$ to the class G of binary classifiers

Theorem: Assume that S is finite. let $(x_1, y_1), \dots, (x_n, y_n)$ be the training data such that $n \in \frac{|S|}{2}$.

Then for any algorithm A , \exists some distribution Π over S and $g^* : Y = g^*(x)$ but $\Pr(\hat{g}(x) \neq g^*(x)) \geq \frac{1}{8}$ with prob $\frac{1}{8}$ where $\hat{g} = A((x_i, y_i)_{i=1}^n)$ P(可得算法犯错概率 > 1/8) > 1/8

Proof: let $\mathcal{X} = \{(x_1, y_1), \dots, (x_n, y_n)\}$

consider $\max_{g^*, \Pi} E_{\mathcal{X}} E_{x \sim \Pi} I[\hat{g}(x) \neq g^*(x)]$

$$\Pr(\hat{g}(x) \neq g^*(x)) \geq c > 0$$

$\frac{1}{8}$
want

pick $g^{*(1)}, g^{*(2)}, \dots, g^{*(k)}$

$$\max_{g^*} E_{\mathcal{X}} E_{x \sim \Pi} I[\hat{g}(x) \neq g^*(x)]$$

最大值 > expected

consider a random g^* s.t. $\forall x \in S, g^*(x) = \begin{cases} +1 & \text{with prob } \frac{1}{2} \\ -1 & \text{with prob } \frac{1}{2} \end{cases}$ independently.

call this distribution \mathcal{Q}

$$\begin{aligned} \max_{g^*, \Pi} E_{\mathcal{X}} E_x I[\hat{g}(x) \neq g^*(x)] &\geq E_{g^* \sim \mathcal{Q}} E_{\mathcal{X}} E_x I[\hat{g}(x) \neq g^*(x)] \\ &= E_{\mathcal{X}} E_x E_{g^* \sim \mathcal{Q}} I[\hat{g}(x) \neq g^*(x)] \\ &\geq E_{\mathcal{X}} E_x \frac{1}{2} I[x \notin \{x_1, \dots, x_n\}] \end{aligned}$$

$$E_{g^* \sim \mathcal{Q}} I[\hat{g}(x) \neq g^*(x)] = \begin{cases} 0 & \text{if } x \in \{x_1, \dots, x_n\} \quad \text{如果见过, 那么会是对的} \\ \frac{1}{2} & \text{if } x \notin \{x_1, \dots, x_n\} \quad \text{如果没见过, 那么有一半概率会对} \end{cases}$$

$$\begin{aligned} &\geq E_{\mathcal{X}} \frac{1}{2} \cdot \frac{1}{2} \\ &= \frac{1}{4} \end{aligned}$$

[lemma] let Z be a r.v. such that $0 \leq Z \leq 1$, then $\Pr(Z \geq \delta) \geq E(Z) - \delta$

proof: $E Z = E Z \cdot I\{Z \leq \delta\} + E Z \cdot I\{Z > \delta\}$
 $\leq \delta + \Pr(Z > \delta)$

\therefore Applying the lemma, we get that

$$\max_{g^*} \Pr_{\mathcal{X}} (\Pr(\hat{g}(x) \neq g^*(x)) \geq \frac{1}{8}) \geq \frac{1}{4} - \frac{1}{8} = \frac{1}{8}$$

$$(\because E_{\mathcal{X}} (\Pr(\hat{g}(x) \neq g^*(x))) = \frac{1}{4})$$

Review of conditional probabilities and conditional expectations

[lemma] let Z be a r.v. s.t. $\text{Var}(Z) < \infty$

$$\text{Then, } EZ = \underset{z \in \mathbb{R}}{\text{argmin}} E(Z-z)^2$$

Proof: let $f(z) = E(Z-z)^2$

$$\text{Then, } f'(z) = 2E(Z-z) = 0 \Leftrightarrow z = EZ$$

$$\text{Finally, } f''(z) = 2 \Rightarrow EZ \text{ is the minimizer} \\ (\text{开口向上})$$

Now, let Z, W be such that $\text{Var}(Z)$ and $\text{Var}(W)$ are finite.

$$\text{Then } E[Z|W=y] = \underset{z \in \mathbb{R}}{\text{argmin}} E_{Z|W=y}(Z-z)^2$$

Clearly, $z = z(y)$ above. Therefore, $E[Z|W=y]$ is a function of W that minimizes $E[(Z-f(W))^2]$ over all functions f .

[Exercise] let $y(w) = E[Z|W]$. Prove that for any function g , $E(Z-y(W)) \cdot g(W) = 0$

let $h(Z)$ be an arbitrary function of Z s.t. $Eh^2(Z) < \infty$
then $E[(W-f(Z)) \cdot h(Z)] = 0$ where $f(Z) = E[W|Z]$

$$\begin{matrix} W \\ \swarrow \searrow \\ f(Z) \end{matrix}$$

$$\langle X, Y \rangle = E(X, Y)$$

Bayes Classifier

$$y(x) = E[Y | X=x] \quad Y \in \{+1, -1\}$$

Theorem: let S be a finite set. X has (discrete) distribution π over S . Then the best possible binary classifier is given by $g^*(x) = \text{sign}(E(Y | X=x))$

$g^*(x)$ is known as Bayes Classifier

Proof: let $g: S \rightarrow \{\pm 1\}$ be arbitrary

$$\text{Then } \Pr(Y \neq g(x)) = \sum_{x \in S} \Pr(Y \neq g(x) | X=x) \cdot \pi(x)$$

probability of $x=x$

$$\Pr(Y=1 | X=x) + \Pr(Y=-1 | X=x) = 1 \quad \left\{ \begin{array}{l} \Pr(Y=1 | X=x) = \frac{1+y(x)}{2} \\ \Pr(Y=-1 | X=x) = \frac{1-y(x)}{2} \end{array} \right. \Leftrightarrow \Pr(Y=t | X=x) = \frac{1+ty(x)}{2}, \quad t \in \{\pm 1\}$$

$$\text{Then } \Pr(Y \neq g(x)) = \sum_{x \in S} \frac{1-g(x)y(x)}{2} \cdot \pi(x)$$

想 minimize

$$\geq \sum_{x \in S} \frac{1-|y(x)|}{2} \pi(x)$$

Equality is achieved when $g(x)y(x) = |y(x)|$ for all $x \in S$

$$\Leftrightarrow \underline{g(x) = \text{sign}(y(x))} \rightarrow \text{Bayes Classifier}$$

Bayes Risk

$$L^* = L(g^*) = \sum_{x \in S} \left(\frac{1-|y(x)|}{2} \right) \pi(x)$$

[Example] 5 cards are drawn at random. 2 are reviewed

$$Y = \begin{cases} 1, & \text{5 cards contain an Ace} \\ -1, & \text{otherwise} \end{cases}$$

Find the Bayes classifier and its risk.

Remark: The risk of the Bayes classifier is called the Bayes risk: $L^* = \Pr(Y \neq g^*(x))$

Solution: $S \in \{1, 0\} \rightarrow \begin{cases} x=1 & \text{if the pair of cards have at least 1 Ace} \\ x=0 & \text{otherwise} \end{cases}$

$$y(x) = E[Y | X=x] = 1 \cdot \Pr(Y=1 | X=x) + (-1) \cdot \Pr(Y=-1 | X=x)$$

$$\Pr(Y=-1 | X=1) = 0$$

$$\Pr(Y=-1 | X=0) = \frac{\binom{46}{2}}{\binom{50}{2}} \approx 0.77$$

$$\Pr(Y=1 | X=1) = 1$$

$$\Pr(Y=1 | X=0) = 1 - \frac{\binom{46}{2}}{\binom{50}{2}}$$

$$y(0) = 1 \cdot (1-0.77) + (-1) \cdot 0.77 = -0.54$$

$$y(1) = 1 \cdot (1-0) + (-1) \cdot 0 = 1$$

$$g^*(x) = \text{sign}(y(x)) = \begin{cases} 1, & x=1 \\ -1, & x=0 \end{cases}$$

$$P(X=1) = 1 - P(\text{both cards are not Aces}) = 1 - \frac{48}{52} \cdot \frac{47}{51} = 0.15$$

$$P(X=0) = 1 - 0.15 = 0.85$$

$$\begin{aligned} L^* &= \frac{1 - P(X=0)}{2} \cdot \Pi(0) + \frac{1 - P(X=1)}{2} \cdot \Pi(1) \\ &= \frac{1 - 0.85}{2} \cdot 0.85 + \frac{1 - 1}{2} \cdot 0.15 \\ &\approx 0.2 \end{aligned}$$

Agnostic PAC-learnability

A class G of binary classifiers is ^(APAC) agnostic PAC-learnable if $\exists m(G; \epsilon, \delta)$ and an algorithm A such that $\forall \epsilon, \delta > 0$, any distribution P of (X, Y) , $LL(\hat{h}_n) \leq \min_{g \in G} L(g) + \epsilon$ with prob $\geq 1 - \delta$ as long as $n \geq m(G; \epsilon, \delta)$

\uparrow
 output of A $L(g^*)$

Next goal: understand which classes are PAC learnable. We will start with finite classes, and then will study infinite classes.

Key idea: concept of uniform closeness of the true and empirical risks.

Definition The training set $X = (X_1, Y_1), \dots, (X_n, Y_n)$ is called ϵ -representative if $L(g) = \Pr(Y \neq g(X))$

$$\forall g \in G, |L_n(g) - L(g)| \leq \epsilon$$

$$L_n(g) = \frac{1}{n} \cdot \#\{1 \leq j \leq n; g(X_j) \neq Y_j\} = \frac{1}{n} \sum_{j=1}^n I\{Y_j \neq g(X_j)\}$$

|empirical risk - true risk| $\leq \epsilon$

[Lemma] Assume that X is $\frac{\epsilon}{2}$ -representative, and let \hat{g}_n be the minimizer of the empirical risk:

$$\hat{g}_n = \operatorname{argmin}_{g \in G} L_n(g). \text{ Then}$$

$$L(\hat{g}_n) = \Pr(Y \neq \hat{g}_n(X) | X) \leq \min_{g \in G} L(g) + \epsilon$$

[proof] let $\bar{g} = \operatorname{argmin}_{g \in G} L(g)$. Then

$$\begin{aligned} L(\hat{g}_n) &= L_n(\hat{g}_n) + L(\hat{g}_n) - L_n(\hat{g}_n) \\ &\leq L_n(\bar{g}) + \max_{g \in G} |L(g) - L_n(g)| \\ &\stackrel{L_n(\hat{g}_n) \leq L_n(\bar{g})}{\leq} L(\bar{g}) + \frac{\epsilon}{2} + |L_n(\bar{g}) - L(\bar{g})| \\ &\stackrel{\substack{\text{已是empirical} \\ \text{最优解}}}{\leq} L(\bar{g}) + \frac{\epsilon}{2} + \frac{\epsilon}{2} \\ &\leq L(\bar{g}) + \epsilon \end{aligned}$$

Bias-Complexity Tradeoff

This concept refers to the following error decomposition:

Let \hat{g} be the output of a learning algorithm A given the training data $\mathcal{X} = (x_1, y_1), \dots, (x_n, y_n)$

Then $L(\hat{g}) = \Pr(Y \neq \hat{g}(x) | \mathcal{X})$

$$= L(\hat{g}) - \min_{g \in G} L(g) + \min_{g \in G} L(g)$$

\geq Bayes Risk L^*

If G is large, $\min_{g \in G} L(g)$ is small. But $L(\hat{g}) - \min_{g \in G} L(g)$ is large

Finite Classes are agnostic PAC learnable

Question: What is the smallest sample size sufficient to guarantee that it is ϵ -representative with probability at least $1 - \delta$?

Assume $|G| < \infty$, then $\Pr(\forall g \in G, |L_n(g) - L(g)| \leq \epsilon)$

$$= 1 - \Pr(\exists g \in G, |L_n(g) - L(g)| > \epsilon)$$

why can apply union bound? $\Pr(\exists g \in G, |L_n(g) - L(g)| > \epsilon)$

$$= \Pr(\cup_{g \in G} \{|L_n(g) - L(g)| > \epsilon\})$$

we need to show the measure of $L_n(g)$ is concentrated around its expected value

$$\leq \sum_{g \in G} \Pr(|L_n(g) - L(g)| > \epsilon)$$

$$\leq |G| \max_{g \in G} \Pr(|L_n(g) - L(g)| > \epsilon)$$

apply Chebyshev's inequality: $P(|x - E(x)| \geq k) \leq \frac{\sigma^2}{k^2}$

Fix $g \in G$, $\Pr(|\frac{1}{n} \sum_{j=1}^n I\{Y_j \neq g(x_j)\} - L(g)| > \epsilon)$

$$L(g) = E L_n(g)$$

$$Z_j = I\{Y_j \neq g(x_j)\}$$

Z_1, \dots, Z_n are i.i.d. $\rightarrow Z$

$$\Pr(|\frac{1}{n} \sum Z_j - E Z| > \epsilon) \leq \frac{\text{Var}(\frac{1}{n} \sum Z_j)}{\epsilon^2}$$

$$\text{Var}(\frac{1}{n} \sum z_j) = \sum \text{Var}(\frac{1}{n} Z_j) = n \cdot \frac{1}{n^2} \text{Var}(Z) = \frac{\text{Var}(Z)}{n}$$

$$\leq |G| \frac{\text{Var}(Z)}{n \epsilon^2} \rightarrow \Pr(\mathcal{X} \text{ is not } \epsilon\text{-representative})$$

$$\frac{|G| \text{Var}(Z)}{n \epsilon^2} \leq \delta \Rightarrow n \geq \frac{|G| \text{Var}(Z)}{\delta \epsilon^2} \quad \text{! Bad Bound}$$

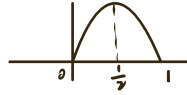
$$\Pr(Z=1) = \Pr(Y \neq g(x)) = P_g$$

$$\Pr(Z=0) = 1 - P_g$$

$$\text{Var}(Z) = P_g(1 - P_g) \leq \frac{1}{4}$$

$$f(x) = x(1-x)$$

→ suppose Bernoulli distribution



$$\therefore \Pr(\exists \text{ not } \epsilon\text{-representative}) \leq |G| \cdot \frac{1}{4n\epsilon^2}$$

[Exercise] $|G| = 1000$

we want \exists ϵ -representative with prob at least 0.9 and $\epsilon = 0.1$ ($\delta = 0.1$)

$$|G| \cdot \frac{1}{4n\epsilon^2} \leq 0.1 = \delta$$

$$n \geq \frac{|G|}{4\delta\epsilon^2} = \frac{10^3}{4 \times 10^{-3}} = 250,000 \quad \text{很大, bad estimation}$$

$\therefore \exists$ ϵ -representative with prob $1 - \delta$

$\Leftrightarrow \hat{g}_n$ obtained by ERM satisfy $L(\hat{g}_n) \leq \min_{g \in G} L(g) + 2\epsilon$ with prob $1 - \delta$

Hoeffding's Inequality

Lemma 4.5 (Hoeffding's Inequality). Let $\theta_1, \dots, \theta_m$ be a sequence of i.i.d. random variables and assume that for all i , $\mathbb{E}[\theta_i] = \mu$ and $\mathbb{P}[a \leq \theta_i \leq b] = 1$. Then, for any $\epsilon > 0$

$$\mathbb{P}\left[\left|\frac{1}{m} \sum_{i=1}^m \theta_i - \mu\right| > \epsilon\right] \leq 2 \exp\left(-2m\epsilon^2 / (b-a)^2\right).$$

apply Hoeffding's inequality to question:

let θ_i be the random variable $L_n(g)$, $\theta_1, \dots, \theta_n$ are i.i.d.

($\because L_n(g)$ is the sample data is i.i.d. RVs)

$$L_n(g) = \frac{1}{n} \sum_{i=1}^n \theta_i, \quad L(g) = \mathbb{E}L_n(g) = \mu$$

$$\therefore \Pr\left(\left|\frac{1}{n} \sum_{i=1}^n \theta_i - \mu\right| > \epsilon\right) \leq 2e^{-2n\epsilon^2}$$

$$\therefore \Pr(\exists g \in G, |L_n(g) - L(g)| > \epsilon) \leq \sum_{g \in G} 2e^{-2n\epsilon^2} = 2|G|e^{-2n\epsilon^2}$$

$$\therefore n \geq \frac{\log\left(\frac{2|G|}{\delta}\right)}{2\epsilon^2} \quad \text{then } \Pr(\exists g \in G, |L_n(g) - L(g)| > \epsilon)$$

$$\text{对于上面 Ex.}, n \geq \frac{1}{2} \cdot 100 \cdot \log\left(\frac{2 \cdot 10^3}{0.1}\right) \leq 2000$$

more reasonable estimation

[Exercise] $S = \{0, 1, 2, 3, 4\}$ X is binomial $B(4, \frac{1}{2})$, $Y \in \{+1, -1\}$

$Pr(Y=1|X=x) = \frac{1}{2}$ (label is random guess)

consider $g(x) = \begin{cases} 1, & x \text{ is even} \\ -1, & x \text{ is odd} \end{cases}$

interpretation: $L(g) = Pr(Y \neq g(x)) = \frac{1}{2}$

$\eta(x) = E[Y|X=x] = 0$

$g^*(x) = \text{sign}(\eta(x)) = \text{either } +1 \text{ or } -1$

Now, $Pr(Y=1|X=x) = \begin{cases} \frac{3}{4} & x=0, 1, 2 \\ \frac{1}{4} & x=3, 4 \end{cases}$

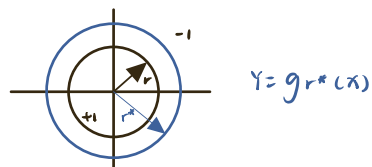
$\Rightarrow Pr(Y=-1|X=x) = \begin{cases} \frac{1}{4} & x=0, 1, 2 \\ \frac{3}{4} & x=3, 4 \end{cases}$

$L(g) = Pr(Y \neq g(x)) = \sum Pr(Y \neq g(x)|X=x) \cdot Pr(X=x)$
 $= \underbrace{(\frac{1}{2})^4 \times \frac{1}{4}}_{x=0} + \underbrace{(\frac{1}{2})^4 \times \frac{1}{4}}_{x=1} + \underbrace{(\frac{1}{2})^4 \times \frac{1}{4}}_{x=2} + \underbrace{(\frac{1}{2})^4 \times \frac{1}{4}}_{x=3} + \underbrace{(\frac{1}{2})^4 \times \frac{1}{4}}_{x=4}$

$X \sim \text{Bin}(n, p)$
 $Pr(X=k) = \binom{n}{k} p^k (1-p)^{n-k}$

[Exercise] $S = \mathbb{R}^2$, $G = \{g_r, r > 0\}$

$g_r(x) = \begin{cases} +1, & \|x\| \leq r \\ -1, & \|x\| > r \end{cases}$ Assume realizability



Show that G is PAC-learnable

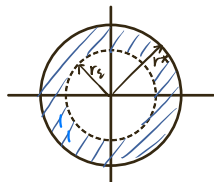
→ show 2 things: (a) An algorithm $A \rightarrow \text{ERM}$

(b) $m \in \mathbb{N}, \delta \in (0, 1)$ s.t. $\hat{g} = \hat{A}(x_1, y_1, \dots, x_m, y_m)$ satisfies $Pr(L(\hat{g}) \geq \epsilon) \leq \delta$

ERM outputs \hat{g} that minimizes $\#\{1 \leq j \leq m; Y_j \neq g(x_j)\}$

$\therefore L_n(\hat{g}) = 0$

$\hat{r} = \min \{r > 0 : \|x_j\| < r \Leftrightarrow Y_j = +1\}$



let r_ϵ be s.t. $Pr(r_\epsilon \leq \|x\| \leq r^*) = \epsilon$

(i) $Pr(\|x\| \leq r^*) < \epsilon \Rightarrow$ Circle $(r=r^*)$ 面积小于 $\epsilon \Rightarrow$ 所有 classifier loss 都小于 ϵ

(ii) $Pr(\|x\| \leq r^*) > \epsilon$

$Pr(L(\hat{g}) \geq \epsilon) = Pr(\hat{r} < r_\epsilon) = Pr(\text{there are no instances with label } +1 \text{ in the ring between circle of radius } r_\epsilon \text{ and } r^*)$

$= Pr(\|x_j\| > r^* \text{ or } \|x_j\| < r_\epsilon \text{ for all } j)$

$= \prod_{j=1}^m Pr(\|x_j\| > r^* \text{ or } \|x_j\| < r_\epsilon)$

$$= (1-\epsilon)^n \leq e^{-\epsilon n}$$

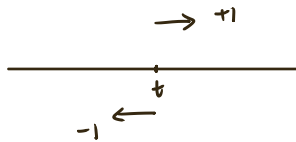
To have $e^{-\epsilon n} \geq \delta$, $n \geq \frac{\log(\frac{1}{\delta})}{\epsilon}$

$(\because \Pr(r \leq \epsilon \|x\| \leq r^*) = \epsilon)$

$(\Leftrightarrow \text{finite class: } n \geq \frac{\log(\frac{16n}{\delta})}{\epsilon})$

[Exercise] let $S = \mathbb{R}$, $G = \{g_t, t \in \mathbb{R}\}$, $g_t(x) = \begin{cases} +1, & x \geq t \\ -1, & x < t \end{cases}$

Prove that G is PAC-learnable assume realizability



Vapnik - Chervonenkis

Question: Which classes G are agnostic PAC learnable?

observation: let $(x_1, y_1), \dots, (x_n, y_n)$ be the training data, and G is the concept class

consider $G_c = \{g(x_1), \dots, g(x_n), g \in G\}$

note that $|G_c| \leq 2^n$

from exercise, we have g_r (linear classifier)

g_r $\|x_1\|, \dots, \|x_n\|$

i_1, \dots, i_n is a permutation such that $\|x_{i_1}\| \leq \|x_{i_2}\| \leq \dots \leq \|x_{i_n}\|$

$\Rightarrow \{(g_r(x_{i_1}), \dots, g_r(x_{i_n})), g_r \in G\}$

can tell $y_{ij} = \begin{cases} +1 & \Rightarrow y_{ik} = +1 \quad \forall k \leq j \\ -1 & \Rightarrow y_{ik} = -1 \quad \forall k \geq j \end{cases}$

\Rightarrow at most $(n+1)$ vectors

\rightarrow what makes it PAC-learnable

Let $(x_1, y_1), \dots, (x_n, y_n)$ is the training data

G is the concept class

$C = \{x_1, \dots, x_n\}$. The set $G_C = \{g(x_1), \dots, g(x_n)\}, g \in G\}$

G_C : restriction of G onto C .

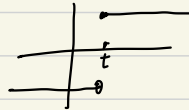
$$|G_C| \leq 2^n$$

If $|G_C| = 2^n$, we will say G shatters C

Remark: C can be an arbitrary finite set

Ex $G = \{g_t, t \in \mathbb{R}\}$

$$g_t(x) = \begin{cases} +1, & x \geq t \\ -1, & x < t \end{cases}$$

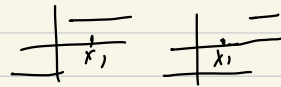


Shift t to get ± 1 for x_i

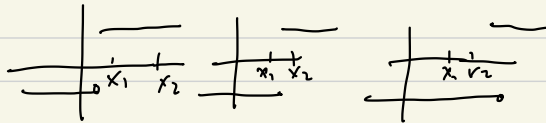
$$C = \{x_1\}$$

$$G_C = \{g_t(x_1), t \in \mathbb{R}\} = \{+1, -1\}$$

shatters



$$C = \{x_1, x_2\}$$



$(+1, +1)$ $(-1, +1)$ $(-1, -1)$

~~$(+1, -1)$~~

$$G_C = \{(1, 1), (-1, -1), (-1, +1)\}$$

no shatter

Def $VC(G)$ - the Vapnik-Chervenkis dimension of G - is the largest d such that $\exists \{x_1, \dots, x_d\}$ that is shattered by G

Remark: $VC(G) = d \iff \{ \exists \{x_1, \dots, x_d\} \text{ shattered by } G \}$
 any set $\{x_1, \dots, x_{d+1}\}$ is not shattered by G .

Remark: we will prove the "Fundamental theorem of PAC learning"

G is agnostic PAC learnable $\Leftrightarrow VC(G) < \infty$

Ex 2 S is infinite
 $G = \{g_T, T \subseteq S, |T| < \infty\}$

$$g_T(x) = \begin{cases} 1, & x \in T \\ -1, & x \notin T \end{cases}$$

Then $VC(G) = \infty$

Solution: for any $d \geq 1$, we need to find $\{x_1, \dots, x_d\} = C$
 s.t. $|G_C| = 2^d$

Let's take any $\{x_1, \dots, x_d\}$, $G_C = \{g_T(x_1), \dots, g_T(x_d), T \subseteq S, |T| < \infty\}$
 $w = \{+1, -1\}^d$, $J = \{j \mid w_j = +1\}$
 $\{+1, -1, -1, -1, +1, \dots, +1\}$
 $\underbrace{\quad}_1 \quad \quad \quad \underbrace{\quad}_d$

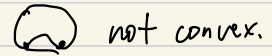
Take $T = \{x_j, j \in J\} \Rightarrow (g_T(x_1), \dots, g_T(x_d)) = w$

Ex 3 $G = \{g_A, A \text{ is convex set}\}$

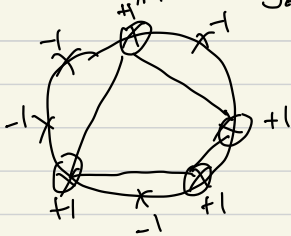
$S = \mathbb{R}^2$ $g_A(x) = \begin{cases} 1, & x \in A \\ -1, & x \notin A \end{cases}$



convex



not convex.



$VC(G) = \infty$

Ex 4

G is finite $VC(G) < \infty$

$\{x_1, \dots, x_d\} = C$

$G_C = \{g(x_1), \dots, g(x_d)\}, g \in G\}$

if $|G_C| \leq |G|$
 $VC(G) = d \Rightarrow |G_C| = 2^d$

$|G| \geq 2^d \Rightarrow d \leq \lfloor \log_2 |G| \rfloor$
 to integer!

Lemma 1: Let G be a concept class of infinite VC dimension, then G is not PAC-learnable

Proof: G is PAC-learnable if $\forall \epsilon, \delta > 0$,
 $\exists A$ - an algorithm and $m = m(\epsilon, \delta)$ m # of training data must form.
 then if $(x_1, y_1), \dots, (x_n, y_n)$ is the training data and
 $n \geq m(\epsilon, \delta)$ then $\Pr(L(\hat{g}) \geq \epsilon) \leq \delta$, $\hat{g} = A((x_1, y_1), \dots, (x_n, y_n))$

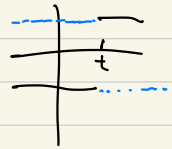
$VC(G) = \infty \Rightarrow \forall m \geq 1, \exists \{x_1, \dots, x_m\} \subseteq S$, such that G shatters $\{x_1, \dots, x_m\}$
 \Rightarrow for any $z \in \{+1, -1\}^m$, $\exists g \in G$ st $z = (g(x_1), \dots, g(x_m))$
 $G_c = \{+1, -1\}^m$

Take $\epsilon = \frac{1}{8}$, $\delta = \frac{1}{10}$

Take N arbitrarily large. Find $C = \{x_1, \dots, x_N\}$ shattered by G
 By no free lunch theorem for any A , $\max_{g^*} \Pr(L(g) \geq \frac{1}{8}) \geq \frac{1}{8}$

Proved by contradiction.

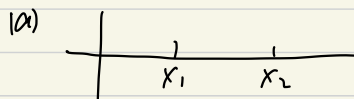
EX 1: $G = \{g_t^+, g_t^-, t \in \mathbb{R}\}$
 $S = \mathbb{R}$, $g_t^+ = \begin{cases} 1 & x > t \\ -1 & x < t \end{cases}$ $g_t^- = \begin{cases} 1 & x < t \\ -1 & x > t \end{cases}$



Then $VC(G) = 2$ (Prove this)

(a) Find two points $\{x_1, x_2\}$ that are shattered.

(b) Show no set of ≥ 3 points are shattered.



$(+1, +1) \rightarrow g_t^+, t < x_1$

$(+1, -1) \rightarrow g_t^-, t \in (x_1, x_2)$

$(-1, +1) \rightarrow g_t^+, t \in (x_1, x_2)$

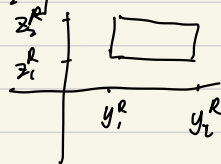
$(-1, -1) \rightarrow g_t^-, t > x_2$

(b) $(-1, +1, -1)$

$(+1, -1, +1)$ Nope

Ex 2: $S = \mathbb{R}^2$, $G = \{g_R, R \text{ is axis-aligned rectangle}\}$

$$g_R = \begin{cases} +1, & x_1 \in [y_1^R, y_2^R], x_2 \in [z_1^R, z_2^R] \\ -1, & \text{else} \end{cases}$$



(a) x_1, x_2, x_3, x_4, x_5 just need one example

(b) no 5 points are shaded

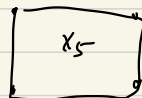
WLOG, assume that x_1 has the largest coordinate.

x_2 has the smallest x coordinate

x_3 has the largest y coordinate

x_4 has the smallest y coordinate

x_5 will be inside the rectangle with -1 which is impossible.



Theorem (R. Dudley) (not in textbook)

Let L be a finite-dimensional space of function $f: S \rightarrow \mathbb{R}$. Consider

$$C_f = \{f \mid \int x : f(x) > 0\}, f \in L \text{ and } \bar{C}_f = \{f \mid \int x^2 : f(x) > 0\}, f \in L \}$$

$$\text{Let } G = \{I_{C_f} - I_{\bar{C}_f}, f \in F\} \quad \bar{G} = \{I_{\bar{C}_f} - I_{C_f}, f \in F\}$$

$$\text{Then } \text{VC}(G) = \text{VC}(\bar{G}) = \text{dim}(L)$$

Finite dim: \mathbb{R}^d $L = \{ \langle a, x \rangle + b, a \in \mathbb{R}^d, b \in \mathbb{R} \}$

$$a \in \mathbb{R}^d \Rightarrow a = a_1 e_1 + \dots + a_d e_d$$

$$e_j = (0, \dots, 0, 1, 0, \dots, 0)$$

↑
j

$$\langle a, x \rangle + b = a_1 \langle e_1, x \rangle + \dots + a_d \langle e_d, x \rangle + b$$

$$\text{dim}(L) = d+1$$

↓
constant

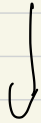
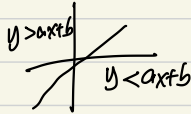
Example

Polynomials of degree at most d ,
 $f(x) = a_0x^d + a_1x^{d-1} + \dots + a_d x + a_{d+1}$

$$\dim(L) = d+1$$

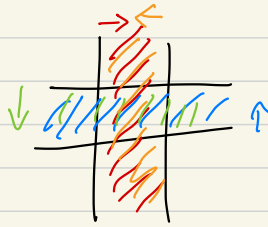
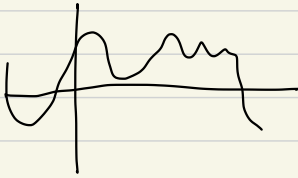
$$y = ax + b \quad \{ (x, y) : y - ax - b > 0 \}$$

$$y - ax - b < 0$$



$$a_1x + a_2y + b = 0$$

$$\dim = 3 = VC(G) = VC(\bar{G})$$



rectangle formation:
intersection of
4 half subspaces
 $\dim \times 4 = 12$ (upper bound?)
 $\frac{1}{3}$

Proof for (R. Dudley): $VC(G) \leq \dim(L)$

Let $\dim(L) = d$, We need to show no set of $d+1$ points is shattered by G .

Take $\{x_1, \dots, x_{d+1}\}$, Consider $T(f) = (f(x_1), \dots, f(x_{d+1}))$ $d+1$

$$T(\alpha f + \beta g) = \alpha T(f) + \beta T(g)$$

Note that $\dim(\text{Image}(T)) \leq d$ because $\dim(L) = d$ and linear maps don't increase dimension.

$\exists w \in \mathbb{R}^{d+1}$ such that $w \perp \text{Image}(T)$

and $w \neq 0$, hence, if $w = (w_1, w_2, \dots, w_{d+1})$

$\Rightarrow \exists j$ st $w_j < 0$ (if $w_j > 0$, take $-w$ instead)

$$A_- = \{j : 1 \leq j \leq n : w_j < 0\} \quad A_+ = \{j : 1 \leq j \leq n : w_j \geq 0\}$$

Assume that $\{x_1, \dots, x_{d+1}\}$ is shattered by G

Since every $g \in G$ is $\text{sign}(f)$ for some $f \in F$.

$\exists f \in F$ st $f(x_j) > 0, j \in A_-$, $f(x_j) < 0, j \in A_+$



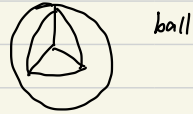
On one hand, since $w \perp \ln(T)$

$$\sum_{j=1}^{d+1} w_j f(x_j) = 0$$

On the other hand, $\sum_{j=1}^{d+1} w_j f(x_j) = \underbrace{\sum_{j \in A_-} w_j f(x_j)}_{\leq 0} + \underbrace{\sum_{j \in A_+} w_j f(x_j)}_{\leq 0} < 0$

Contradiction $\Rightarrow \{x_1, \dots, x_{d+1}\}$ cannot be shattered by G .

Example: $B_d(x, r) = \{y \in \mathbb{R}^d, \|y - x\|_2 \leq r\}$
 $G = \{g : \mathbb{R}^d \rightarrow \{-1, 1\}\}$, where
 $g = g_{x,r}$, and $g_{x,r}(y) = \begin{cases} 1, & y \in B_d(x, r) \\ -1, & \text{else} \end{cases}$



Then $VC(G) \leq d+2$

Express definition of a ball as $f(y) \geq 0$ for $f \in L$, where $\dim(L) = d+2$

$$\text{norm} = \sqrt{\sum_{j=1}^d (y_j - x_j)^2} \leq r \Leftrightarrow \sum_{j=1}^d (y_j - x_j)^2 \leq r^2 \Leftrightarrow \sum_{j=1}^d (y_j^2 - 2x_j y_j + x_j^2) \leq r^2$$

$$\Leftrightarrow -\left(\sum_{j=1}^d y_j^2 - 2 \sum_{j=1}^d x_j y_j + \sum_{j=1}^d x_j^2 - r^2 \right) \geq 0$$

$$f_1(y_1, \dots, y_d) = \sum_{j=1}^d y_j^2 \quad f_2(y_1, \dots, y_d) = y_1 \quad \dots \quad f_{d+1}(y_1, \dots, y_d) = y_d$$

$$f_{d+2}(y_1, \dots, y_d) = 1$$

$$f(y_1, \dots, y_d) = -1 \cdot f_1 + 2x_1 f_2 + 2x_2 f_3 + \dots + 2x_d f_{d+1} + \left(\sum_{j=1}^d x_j^2 - r^2 \right) f_{d+2}$$

$$\Rightarrow f(y_1, \dots, y_d) \in L \text{ and } \dim(L) = d+2$$

$C = \{x_1, \dots, x_k\}$, G - concept class, $G_C = \{g(x_1) \dots g(x_k) : g \in G\}$

Assume that $VC(G) = d$. Then $\exists \{x_1, \dots, x_d\} = C_d$ st $|G_{C_d}| = 2^d$

What if $k > d$? What can we say about $|G_C|$? (beyond the fact that $|G_C| < 2^k$)

Def (The growth function)

$$\tau_G(k) = \max |G_C| \quad C = \{x_1, \dots, x_k\}$$

Lemma (Shelah-Sauer-Porles - Vapnik-Chervonenski)

Let G be such that $VC(G) = d$.

$$\text{Then } \tau_G(k) \leq \sum_{j=0}^d \binom{k}{j} \quad \binom{k}{j} = \frac{k!}{j!(k-j)!}$$

$$\text{If } k \leq d, \tau_G(k) \leq \sum_{j=0}^k \binom{k}{j} = 2^k$$

$$\text{For } k > d, \sum_{j=0}^d \binom{k}{j} \leq \left(\frac{ek}{d}\right)^d$$

Proof:

$$\binom{k}{j} = \frac{k!}{j!(k-j)!} = \frac{k(k-1)\dots(k-j+1)}{j!}$$

$$= \frac{k}{d} \frac{(k-1)}{d} \dots \frac{(k-j+1)}{d} \cdot \frac{d^j}{j!} < \left(\frac{k}{d}\right)^j \frac{d^j}{j!}$$

$$< \frac{k}{d} \frac{d^j}{j!} \leq \left(\frac{k}{d}\right)^d \frac{d^j}{j!}$$

$$\sum_{j=0}^d \binom{k}{j} \leq \sum_{j=0}^d \left(\frac{k}{d}\right)^d \frac{d^j}{j!} = \left(\frac{k}{d}\right)^d \sum_{j=0}^{\infty} \frac{d^j}{j!} = \left(\frac{ek}{d}\right)^d$$

Exercise: $\sum_{j=0}^d \binom{k}{j} \geq \left(\frac{k}{d}\right)^d$

Recap

G - class of binary classifiers

$$\tau_a(m) = \max_{C = \{x_1, \dots, x_m\} \subset S} |G_C|$$

Lemma If $VC(G) = d < \infty$, then $\tau_a(m) \leq \left(\frac{me}{d}\right)^d$ for all $m > d$

Example: Let G_1, G_2 be two classes of binary classifiers, Prove intersection is finite

$$VC(G_1) = d_1 < \infty, VC(G_2) = d_2 < \infty$$

$$\text{Let } C_{G_i} = \{x \mid g(x) = +1\}, g \in G_i\}$$

$i=1,2$

$$C_{G_1} \cap C_{G_2} = \{C_1 \cap C_2 \mid C_1 \in C_{G_1}, C_2 \in C_{G_2}\}$$

Let G be the set of all classifiers

$$g(x) = \begin{cases} 1, & x \in C \text{ for } C \in C_{G_1} \cap C_{G_2} \\ -1, & \text{else} \end{cases}$$

↓ intersection
↓

Proof: $VC(G) < \infty$

idea: If we can show that $\tau_G(m) = O(m^V)$ for some $V < \infty$, then $VC(G) < \infty$

Fix some $\{x_1, \dots, x_m\} = M$

Consider the set $|M \cap \{f : x : g(x) = +1\}, g \in G_1\}| \leq \tau_{G_1}(m)$

illustrate:

$$g_t(x) = \begin{cases} +1, & x < t \\ -1, & x > t \end{cases}$$

$\frac{+}{-} \frac{+}{-} \frac{+}{-}$
 $x_1 \quad x_2 \quad x_3$

$$M = (x_1, x_2, x_3)$$

$$M \cap \{f : x : g(x) = +1\} \mid g_t \in G_1 = \{(x_1, x_2, x_3), (x_2, x_3), \emptyset\}$$

$$G_1 = \{(+, +, +), (-, +, +), (-, -, +), (-, -, -)\}$$

$$M \cap \{f : x : g_1(x) = +1\}, g_1 \in G_1 = M_{G_1}$$

$$M \cap \{f : x : g_2(x) = +1\}, g_2 \in G_2 = M_{G_2}$$

$$C_1 \in M_{G_1}, \quad \begin{matrix} \oplus & \bullet \\ \ominus & \ominus \end{matrix} \quad |C_1 \cap M_{G_2}| \leq |M_{G_2}| = \tau_{G_2}(m)$$

$$\begin{matrix} \oplus & \bullet \\ \ominus & \ominus \end{matrix} \Rightarrow |M_{C_1} \cap M_{G_2}| \leq |M_{C_1}| \cdot |M_{G_2}| \leq \tau_{G_1}(m) \cdot \tau_{G_2}(m)$$

$G_1 \quad G_2 \quad G_1 \quad G_2$
10K

$$\tau_G(m) \leq \tau_{G_1}(m) \cdot \tau_{G_2}(m)$$

$$\leq \left(\frac{me}{d_1}\right)^{d_1} \cdot \left(\frac{me}{d_2}\right)^{d_2} = O(m^{d_1+d_2})$$

$$\Rightarrow VC(G) < \infty$$

Example: $G_1 = \{g_t^+, t \in \mathbb{R}\}$ $\frac{+}{-}$ $VC(G_1) = 1$
 $G_2 = \{g_t^-, t \in \mathbb{R}\}$ $\frac{+}{-}$ $VC(G_2) = 1$

$$G = \{g_{[a,b]}, a, b \in \mathbb{R}\}$$

$$g_{[a,b]}(x) = \begin{cases} +1, & x \in [a,b] \\ -1, & \text{else} \end{cases}$$

$$\tau_G(m) \leq \tau_{G_1}(m) \tau_{G_2}(m)$$

$$\tau_{G_1}(m) = m+1, \quad \tau_{G_2}(m) = m+1$$

$$\tau_G(m) = \binom{m+1}{2} = \frac{m(m+1)}{2} \leq (m+1)^2$$

$$\begin{matrix} + & + & + \\ - & + & + \\ - & - & + \\ - & - & - \\ + & + & - \\ - & - & - \end{matrix}$$

$(X_1, Y_1) \dots (X_n, Y_n)$ is ϵ -representative if

$$\max_{g \in G} \left| \frac{1}{n} \sum_{i=1}^n \mathbb{I}\{Y_i \neq g(X_i)\} - \underbrace{L(g)}_{\Pr(Y \neq g(X))} \right| \leq \epsilon$$

Theorem: Let G be a concept class (a class of binary classifiers) and let $\tau_G(n)$ be its growth function.

Then $\max_{g \in G} \left| \frac{1}{n} \sum_{i=1}^n \mathbb{I}\{Y_i \neq g(X_i)\} - L(g) \right| \leq \frac{\sqrt{2 \log(2) \tau_G(n)}}{\delta \sqrt{n}}$ with probability at least $1 - \delta$.

with probability at least $1 - \delta$.

It's sufficient to prove that $\mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{i=1}^n \mathbb{I}\{Y_i \neq g(X_i)\} - L(g) \right| \leq \frac{\sqrt{2 \log(2) \tau_G(n)}}{\sqrt{n}}$

It's because

$$\Pr(Z > t) \leq \frac{\mathbb{E}Z}{t} \quad \text{- Markov's inequality.}$$

$$\Pr(Z > \frac{\mathbb{E}Z}{\delta}) \leq \frac{\mathbb{E}Z}{\frac{\mathbb{E}Z}{\delta}} \delta = \delta$$

For (agnostic) PAC-learnability, we need

(a) An algorithm \mathcal{A}

(b) $n(\epsilon, \delta)$

s.t. given $(X_1, Y_1) \dots (X_n, Y_n)$ with $n \geq n(\epsilon, \delta)$, \mathcal{A} outputs g_n st $\Pr(L(g_n) > \epsilon) \leq \delta$

In our case, if \mathcal{A} is ERM, we know that $\epsilon/2$ -representative sample yields a classifier $L(g) \leq \epsilon$

Doing some algebra, we get $n \geq K \frac{1}{\delta^2 \epsilon^2} \log\left(\frac{1}{\delta^2 \epsilon^2}\right)$, $K = \text{constant}$

Symmetrization inequality:

let $\sigma_1, \dots, \sigma_n$ be random signs,
 i.e. iid random variables st $\Pr(\sigma_i = 1) = \Pr(\sigma_i = -1) = \frac{1}{2}$

$$\mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n I \{Y_j \neq g(X_j)\} - L(g) \right| \leq 2 \mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j I \{Y_j \neq g(X_j)\} \right|$$

↓
 inner product $\langle (\sigma_1, \dots, \sigma_n), (I \{Y_1 \neq g(X_1)\}, \dots, I \{Y_n \neq g(X_n)\}) \rangle$
 like random noise

Theorem G - a class of binary classifiers

$$\max_{g \in G} |L_n(g) - L(g)| \leq \frac{4}{\delta} \sqrt{\log(2 T_n(n))}$$

with probability $\geq 1 - \delta$ over the choice of the sample $(X_1, Y_1), \dots, (X_n, Y_n)$

In other words, if \rightarrow sample size n as a function of ϵ, δ

$$n(\epsilon, \delta) \geq \frac{\log \frac{V(G)}{\delta^2 \epsilon^2} \log \left(\frac{V}{\delta^2 \epsilon^2} \right)}$$

$\Rightarrow \hat{g}_n$ produced by ERM when given a sample of size $n(\epsilon, \delta)$ satisfies
 $\Pr(L(\hat{g}_n) > \min_{g \in G} L(g) + \epsilon) \leq \delta \rightarrow$ defn of PAC-learnability

It suffices to show that

$$\mathbb{E} \max_{g \in G} |L_n(g) - L(g)| \leq \frac{4}{\sqrt{n}} \sqrt{\log(2 T_n(n))}$$

Symmetrization inequality:

$$\mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n I \{Y_j \neq g(X_j)\} - L(g) \right| \leq 2 \mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j I \{Y_j \neq g(X_j)\} \right|$$

$\sigma_1, \dots, \sigma_n$ iid random signs independent from $(X_1, Y_1), \dots, (X_n, Y_n)$, i.e. $\Pr(\sigma_i = 1) = \Pr(\sigma_i = -1) = \frac{1}{2}$

Note that $\mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j I \{Y_j \neq g(X_j)\} \right|$

$$\mathbb{E}_{(x_j, y_j)_{j=1}^n} \mathbb{E}_{\sigma_1, \dots, \sigma_n} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j \mathbb{I} \{y_j \neq g(x_j)\} \right|$$

$t_j \in \{0, 1\}$

focus on this.

$$t = (t_1, \dots, t_n)$$

$$\mathbb{E}_{\sigma_1, \dots, \sigma_n} \max_{t \in T} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j t_j \right|$$

Remark: $\left\{ \mathbb{I} \{y_1 \neq g(x_1)\}, \dots, \mathbb{I} \{y_n \neq g(x_n)\}, g \in G \right\}$

$$= \left| G_C \right|, C = \{x_1, \dots, x_n\}$$

"

$$\{(g(x_1), \dots, g(x_n)), g \in G\}$$

-1 1

The number of such vectors is at most $T_G(n)!$

Lemma: Let $t^{(1)}, \dots, t^{(k)} \in \mathbb{R}^n$

Then $\mathbb{E} \max_{j=1, \dots, k} \left| \frac{1}{n} \sum_{i=1}^n \sigma_i t_i^{(j)} \right| \leq 2 \max_{j=1, \dots, k} \frac{\|t^{(j)}\|_2}{\sqrt{n}} \sqrt{\frac{\log(2k)}{n}}$

Exercise $\mathbb{E} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j t_j \right| \leq \frac{1}{\sqrt{n}} \frac{\|t\|_2}{\sqrt{n}}$

Proof: let $f(\lambda) = \mathbb{E} e^{\lambda \sigma_i}$, $s \in \mathbb{R}$

Indeed, $\mathbb{E} e^{\lambda \sigma_i} = e^{\lambda \cdot \frac{1}{2}} + e^{-\lambda \cdot \frac{1}{2}} \cdot \frac{1}{2}$

$$= \frac{1}{2} (e^\lambda + e^{-\lambda}) = \frac{1}{2} \left(1 + \lambda + \frac{\lambda^2}{2!} + \dots + \frac{\lambda^k}{k!} + \dots + 1 - \lambda + \frac{\lambda^2}{2!} + \dots + (-1)^k \frac{\lambda^k}{k!} + \dots \right)$$

$$= \frac{1}{2} \cdot 2 \sum_{k \geq 0} \frac{\lambda^{2k}}{(2k)!} = 1 + \frac{\lambda^2}{2!} + \frac{\lambda^4}{4!} + \dots$$

$$\lambda^{2k} = (\lambda^2)^k \quad (k!) = \underbrace{1 \cdot 2 \cdot \dots \cdot k}_{k!} \underbrace{(k+1)(k+2) \cdot \dots \cdot (2k)}_{\geq 2 \cdot \geq 2 \cdot \geq 2} \geq 2^k \cdot k! \quad \text{for } k \geq 1$$

$$\sum_{k \geq 0} \frac{\lambda^{2k}}{(2k)!} \leq \sum_{k \geq 0} \frac{(\lambda^2)^k}{k! 2^k} = \sum_{k \geq 0} \frac{(\frac{\lambda^2}{2})^k}{k!} = e^{\frac{\lambda^2}{2}}$$

MGF (Moment Generating Function) of $\frac{1}{n} \sum_{j=1}^n \sigma_j t_j$:

$$\begin{aligned} \mathbb{E} e^{\lambda \left(\frac{1}{n} \sum_{j=1}^n \sigma_j t_j \right)} &= \mathbb{E} \left(e^{\frac{\lambda}{n} \sigma_1 t_1} \dots e^{\frac{\lambda}{n} \sigma_n t_n} \right) \\ &= \mathbb{E} e^{\frac{\lambda}{n} \sigma_1 t_1} \times \dots \times \mathbb{E} e^{\frac{\lambda}{n} \sigma_n t_n} \\ &\leq e^{\frac{\lambda^2 \sigma_1^2}{2n}} \dots e^{\frac{\lambda^2 \sigma_n^2}{2n}} = e^{\frac{\lambda^2}{2n} \cdot \frac{\sum_{j=1}^n \sigma_j^2}{n}} = e^{\frac{\lambda^2}{2n} \frac{\|t\|_2^2}{n}} \end{aligned}$$

Next, $x \mapsto e^{\lambda x}$ is convex, i.e. $e^{\lambda \left(\sum_{j=1}^k \alpha_j x_j \right)} \leq \alpha_1 e^{\lambda x_1} + \dots + \alpha_k e^{\lambda x_k}$

$\alpha_1, \dots, \alpha_k \geq 0$
 $\sum_{j=1}^k \alpha_j = 1$

In other words, $\lambda \in \mathbb{R} \implies \mathbb{E} e^{\lambda Z} \leq \sum_{j=1}^k \alpha_j e^{\lambda x_j} = \mathbb{E} e^{\lambda Z}$ where $\Pr(X=x_j) = \alpha_j$

Jensen's inequality

$$Z = \max_{j=1, \dots, k} \left| \frac{1}{n} \sum_{i=1}^n \sigma_i t_i^{(j)} \right| \quad (a| = \max(a, -a))$$

$$e^{\lambda Z} \leq \mathbb{E} e^{\lambda Z} = \mathbb{E} \max_{j=1, \dots, k} \left(\underbrace{e^{\frac{\lambda}{n} \sum_{i=1}^n \sigma_i t_i^{(j)}}}_{\text{V}}, \underbrace{e^{-\frac{\lambda}{n} \sum_{i=1}^n \sigma_i t_i^{(j)}}}_{\text{V}} \right)$$

$2k$ random variables

$$\mathbb{E} \sum_{j=1}^k \left(e^{\frac{\lambda}{n} \sum_{i=1}^n \sigma_i t_i^{(j)}} + e^{-\frac{\lambda}{n} \sum_{i=1}^n \sigma_i t_i^{(j)}} \right) \leq 2 \sum_{j=1}^k \exp\left(\frac{\lambda^2}{n^2} \frac{\|t^{(j)}\|_2^2}{2} \right)$$

$$\leq 2k \exp\left(\frac{\lambda^2}{n^2} \max_{j=1, \dots, k} \frac{\|t^{(j)}\|_2^2}{2} \right)$$

$$e^{\lambda Z} \leq 2k e^{\frac{\lambda^2}{2n^2} \max_j \frac{\|t^{(j)}\|_2^2}{2}}$$

Take log: $\lambda Z \leq \log(2k) + \frac{\lambda}{2n^2} \max_{j=1, \dots, k} \|t^{(j)}\|_2^2$

True for any $\lambda > 0$

$$h(\lambda) = \frac{\log(2k)}{\lambda} + \frac{\lambda}{2n^2} \max_{j=1, \dots, k} \|t^{(j)}\|_2^2$$

$$h'(\lambda) = 0 \iff \lambda_*^2 = \frac{\log(2k)}{2 \frac{1}{n} \max_{j=1, \dots, k} \|t^{(j)}\|_2^2}$$

$$h(\lambda_x) = \sqrt{2} \sqrt{\frac{\log(2k)}{2}} \max_{j=1, \dots, n} \frac{\|t^{(j)}\|_2}{\sqrt{n}}$$

$$\mathbb{E}_{\sigma_1, \dots, \sigma_n} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j \cdot \mathbb{I}\{Y_j \neq g(X_j)\} \right| \leq \sqrt{2} \sqrt{\frac{\log(2k)}{n}} \cdot 1$$

$$t^{(j)} = (\mathbb{I}\{Y_1 \neq g(X_1)\}, \dots, \mathbb{I}\{Y_n \neq g(X_n)\})$$

$$\|t^{(j)}\|_2 = \sqrt{n}$$

Symmetrization inequality

Let G be a class of binary classifiers, and $\sigma_1, \dots, \sigma_n$ are iid random signs, i.e. $\Pr(\sigma_i = 1) = \Pr(\sigma_i = -1) = \frac{1}{2}$

$$\text{Then } \mathbb{E} \max_{g \in G} |L_n(g) - L(g)| = \mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \mathbb{I}\{Y_j \neq g(X_j)\} - \Pr(Y \neq g(X)) \right|$$

$$\leq 2 \mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j \mathbb{I}\{Y_j \neq g(X_j)\} \right|$$

Proof: Let $(X'_1, Y'_1), \dots, (X'_n, Y'_n)$ - an independent copy of $(X_1, Y_1), \dots, (X_n, Y_n)$

Note that $L(g) = \mathbb{E} \left(\frac{1}{n} \sum_{j=1}^n \mathbb{I}\{Y_j \neq g(X_j)\} \right)$

$$\text{Therefore, } \mathbb{E} \max_{g \in G} |L_n(g) - L(g)| = \mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \mathbb{I}\{Y_j \neq g(X_j)\} - \mathbb{E}_{(X', Y')} \left[\frac{1}{n} \sum_{j=1}^n \mathbb{I}\{Y'_j \neq g(X'_j)\} \right] \right|$$

$$\leq \mathbb{E} \max_{(X, Y)} \max_{g \in G} \left| \mathbb{E}_{(X, Y)} \left[\frac{1}{n} \sum_{j=1}^n \mathbb{I}\{Y_j \neq g(X_j)\} - \mathbb{I}\{Y'_j \neq g(X'_j)\} \right] \right|$$

$$|\mathbb{E} Z| \leq \mathbb{E} |Z| \leq \mathbb{E} \max_i |a_i| \leq \max_i |a_i|$$

$$\leq \mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \mathbb{I}\{Y_j \neq g(X_j)\} - \mathbb{I}\{Y'_j \neq g(X'_j)\} \right|$$

$$\max \mathbb{E} Z_i \leq \mathbb{E} \max_i Z_i$$

Note that we can "switch" (X_j, Y_j) with (X'_j, Y'_j) for any j without changing the expectation.

Equivalently, for any fixed $g_1, \dots, g_n \in \{+1, -1\}^n$

$$\leq \mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j \left(\mathbb{I}\{f_j \neq g(x_j)\} - \mathbb{I}\{f_j' \neq g(x_j)\} \right) \right| = \frac{1}{2^n} \sum_{(g_1, \dots, g_n) \in \{-1, 1\}^n} \mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j \left(\mathbb{I}\{f_j \neq g(x_j)\} - \mathbb{I}\{f_j' \neq g(x_j)\} \right) \right|$$

$$= \mathbb{E} \max_{g_1, \dots, g_n} \left(\mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j \left(\mathbb{I}\{f_j \neq g(x_j)\} - \mathbb{I}\{f_j' \neq g(x_j)\} \right) \right| \right)$$

$$|a-b| \leq |a| + |b| \quad \leq 2 \mathbb{E} \max_{g \in G} \left| \frac{1}{n} \sum_{j=1}^n \sigma_j \mathbb{I}\{f_j \neq g(x_j)\} \right|$$

END

The Fundamental Theorem of PAC Learning.

Let G be a class of binary classifiers. Then the following conditions are equivalent:

- (a) G is agnostic PAC learnable via the ERM algorithm.
- (b) G is PAC learnable via the ERM algorithm.
- (c) G has the "uniform convergence" property: $\forall \epsilon, \delta > 0, \exists n(\epsilon, \delta)$ s.t. $\forall n \geq n(\epsilon, \delta)$

$$\max_{g \in G} |L_n(g) - L(g)| \leq \epsilon$$
with probability at least $1 - \delta$.
- (d) G has finite VC dimension.

Proof: (d) \Rightarrow (c)

Moreover, we have shown that $n(\epsilon, \delta) \leq \text{constant} \frac{VC(G)}{\delta^2 \epsilon^2} \log \left(\frac{eVC(G)}{\delta^2 \epsilon^2} \right)$

(c) \Rightarrow (a) (a) \Rightarrow (b) (b) \Rightarrow (d)

Remark

$$C_1 \frac{VC \log \left(\frac{1}{\delta} \right)}{\epsilon^2} \leq n(\epsilon, \delta) \leq C_2 \frac{VC \log \left(\frac{1}{\delta} \right)}{\epsilon^2}$$

End of theory.

Practical stuff

Learning beyond binary classification.

- What if there are 3 or more classes that the objects of interest should be classified into?
- What if the "label" Y takes values in \mathbb{R} ?
- Our theory remains valid modulo minor changes.

"One vs All" Cat vs Dog or Rabbit
 yes no
 cat dog or Rabbit

"1 vs 1": if we have k possible labels, $\{1, \dots, k\}$, consider $\binom{k}{2}$ binary classification problems "X is in class i or X is in class j ". Pick the label that gets most "+1" votes.

- We will talk about general "prediction" problems: predict the "response" Y based on the "predictor" X . Prediction is performed via some function $g \in G$.

Example Multi-label classification
 X is a test paper, $Y \in \{A, B, C, D, F\}$

Example general regression problem
 X = hours spent on social media / week, Y = GPA $\in [1, 4]$

- Need to generalize the notion of the loss function, denoted $l(y, g(x))$
e.g. in binary classification, $l(y, g(x)) = \mathbb{I}\{y \neq g(x)\}$
In multi-label classification, it can be $l(y, g(x)) = \mathbb{I}\{y \neq g(x)\}$
We can also choose

$$l(y, g(x)) = \begin{cases} 0, & y = g(x) \\ 1, & y \neq g(x) \text{ and } y = 0 \\ 100, & y \neq g(x) \text{ and } y = 1 \end{cases}$$

• The goal remaining as before; minimize $\mathbb{E} \ell(Y, g(x))$ over $g \in G$.

• Example Regression problem: $Y \in \mathbb{R}, X \in \mathbb{R}^d$

$$\ell(y, g(x)) = (y - g(x))^2 \quad \leftarrow \text{why squared (MLE)}$$

$$G = \{ \langle w, x \rangle + b, w \in \mathbb{R}^d, b \in \mathbb{R} \}$$

• Ex Assume that $X \in \mathbb{R}$, assume that $Y_j = \alpha X_j + \beta + \varepsilon_j, \alpha, \beta \in \mathbb{R}$
and ε_j is (a) $N(0, \sigma^2)$

(b) Laplace distribution with density $p(x) = \frac{1}{2} e^{-|x|}, x \in \mathbb{R}$

$\varepsilon_1, \dots, \varepsilon_n$ are independent. Show that the MLE of α, β minimizes

(a) $\frac{1}{n} \sum_{j=1}^n (Y_j - \alpha X_j - \beta)^2$ over $\alpha, \beta \in \mathbb{R}$

(b) $\frac{1}{n} \sum_{j=1}^n |Y_j - \alpha X_j - \beta|$

Question of practical importance:

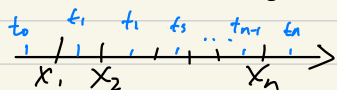
can we implement ERM methods that have strong theoretical guarantees?

Example $S = \mathbb{R}, T = \{-1, +1\}, (X, Y) \in S \times T$

$$G = \{ g_t^+, g_t^- \}, \quad g_t^+(x) = \begin{cases} +1, & x \geq t \\ -1, & x < t \end{cases}, \quad g_t^-(x) = \begin{cases} -1, & x \geq t \\ +1, & x < t \end{cases}$$

(a) Realizable scenario

$$g_n \text{ minimizes } \frac{1}{n} \sum_{j=1}^n I \{ Y_j \neq g(x_j) \} \text{ over } g \in G$$



$x_{(j)}$ is the j th smallest among x_1, \dots, x_n

$O(n \log n)$ to sort. $O(\log n)$ to find t_*

Compare $L(g_{t_1}^+), \dots, L(g_{t_n}^+)$

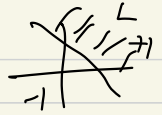
$L(g_{t_1}^-), \dots, L(g_{t_n}^-)$

In agnostic learning framework, we only need to compare the empirical risks of at least $2(n+1)$ classifiers.

What about linear separators in dimension 2?

Specifically, let $S = \mathbb{R}^2$, $T = \{+1, -1\}$

$G = \{g_L, L \rightarrow \text{a half-plane}\}$ $g_L(x) = \begin{cases} 1, & x \in L \\ -1, & x \in L^c \end{cases}$



Let's take a look at the more general problem:

$S = \mathbb{R}^d$, $T = \{+1, -1\}$

The hyperplane is a set of points $\{x \in \mathbb{R}^d : \langle w, x \rangle + b = 0$
 $w \in \mathbb{R}^d, b \in \mathbb{R}\}$



The half-spaces are given by
 $L = \{x \in \mathbb{R}^d : \langle w, x \rangle + b \geq 0\}$

$$\tilde{x} = (x, 1), \quad \tilde{w} = (w, b), \quad \langle w, x \rangle + b = \langle \tilde{w}, \tilde{x} \rangle$$

Realizability there exist w_x s.t. $Y_j = \text{sign}(\langle w_x, x_j \rangle)$

$$\Leftrightarrow Y_j \langle w_x, x_j \rangle > 0$$

Let $\gamma = \min_{j=1, \dots, n} Y_j \langle w_x, x_j \rangle \Rightarrow Y_j \langle \frac{w_x}{\gamma}, x_j \rangle \geq 1 \quad \forall j = 1, \dots, n$

Denote $\tilde{w} = \frac{w_x}{\gamma} \Rightarrow Y_j \langle \tilde{w}, x_j \rangle \geq 1$ for all j .

Can we find such \tilde{w} ?

Perceptron Algorithm (Frank Rosenblatt)

Given $(x_1, Y_1), \dots, (x_n, Y_n)$, let $w_0 = (0, \dots, 0)$
for $t = 1, 2, \dots$

if $\exists 1 \leq j \leq n$ $Y_j \langle w^{(t)}, x_j \rangle \leq 0$

then $w^{(t+1)} = w^{(t)} + Y_j x_j$ else return $w^{(t)}$

Perceptron algorithm ~~the~~ ~~perceptron~~ = gradient descent, descent method

$$\langle w, x_j \rangle > 0 \Leftrightarrow y_j = +1$$

$$\Leftrightarrow y_j \langle w, x_j \rangle > 0, 1 \leq j \leq n$$

$$\gamma = \min_j y_j \langle w, x_j \rangle \Rightarrow \min_j y_j \langle \frac{w}{\gamma}, x_j \rangle = 1$$

Goal: find a vector w s.t. $y_j \langle w, x_j \rangle \geq 1$ for all j

Perceptron Algorithm (Frank Rosenblatt)

Given $(x_1, y_1), \dots, (x_n, y_n)$, let $w_0 = (0, \dots, 0)$

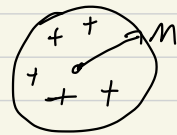
for $t = 1, 2, \dots$

if $\exists 1 \leq j \leq n$ $y_j \langle w^{(t)}, x_j \rangle \leq 0$

then $w^{(t+1)} = w^{(t)} + y_j x_j$ else return $w^{(t)}$

Th Assume that $\max_j \|x_j\| \leq M$

Then the perceptron algorithm stops after at most $(\frac{M}{\gamma})^2$ iterations



Pf: Let $\tilde{w} = \frac{w^*}{\gamma}$ be s.t. $y_j \langle \tilde{w}, x_j \rangle \geq 1$

Consider $\langle w_{t+1}, \tilde{w} \rangle = \langle w_t + y_j x_j, \tilde{w} \rangle = \langle w_t, \tilde{w} \rangle + y_j \langle x_j, \tilde{w} \rangle \geq \langle w_t, \tilde{w} \rangle + 1$

$\Rightarrow \langle w_{t+1}, \tilde{w} \rangle \geq t+1$

At the same time, $\|w_{t+1}\|^2 = \|w_t + y_j x_j\|^2 = \langle w_t + y_j x_j, w_t + y_j x_j \rangle$

$$= \|w_t\|^2 + \|x_j\|^2 + 2y_j \langle w_t, x_j \rangle \leq \|w_t\|^2 + M^2 \leq (t+1)M^2$$

Combine 2 inequalities, $(t+1) \leq \langle w_{t+1}, \tilde{w} \rangle \leq \|w_{t+1}\| \cdot \|\tilde{w}\| \leq M \sqrt{t+1} \cdot \frac{1}{\gamma}$

$$\Rightarrow t+1 \leq \frac{M}{\gamma} \sqrt{t+1} \Rightarrow t+1 \leq \left(\frac{M}{\gamma}\right)^2$$

Perception as the **pseudo**-gradient descent method.

Question: find w st. $\forall_j \langle w, x_j \rangle > 0$ \forall_j

Known: $\exists \tilde{w}$ st. $\forall_j \langle \tilde{w}, x_j \rangle \geq 1$ \forall_j

We can "find" \tilde{w} by minimizing $F(x) = \frac{1}{2} \|x - \tilde{w}\|_2^2$ $\nabla F(x) = x - \tilde{w}$

To minimize any differentiable function F , we can use the gradient descent method:
 let $x_0 = 0$, for $t = 1, 2, \dots, T$, $x_{t+1} = x_t - h \nabla F(x_t)$ $\nabla F(x_1, \dots, x_d) = \left(\frac{\partial F}{\partial x_1}, \dots, \frac{\partial F}{\partial x_d} \right)$

Pseudo-gradient descent: instead of using $\nabla F(x_t)$, assume that we can find v_t such that $\langle \nabla F(x_t), v_t \rangle \geq \delta > 0$. Then define $x_{t+1} = x_t - h \cdot v_t$

$v_t = -\gamma_j x_j$, where $\forall_j \langle w_t, x_j \rangle < 0$ for the perception.

Convergence of GD

Assume that $\forall x, y \in \mathbb{R}^d$

$$\|\nabla F(x) - \nabla F(y)\| \leq L \|x - y\| \quad \text{E.g. if } F(x) = \frac{1}{2} \|x - \tilde{w}\|^2, \text{ then } \nabla F(x) - \nabla F(y) = x - y \Rightarrow L = 1$$

$$\Rightarrow \langle \nabla F(w_t), -h \gamma_j x_j \rangle \geq \underbrace{-h \gamma_j \langle w_t, x_j \rangle}_{> 0} + \underbrace{h \gamma_j \langle w_t, x_j \rangle}_{> h} \geq h$$

Taylor's expansion:

$$F(x+z) = F(x) + \langle \nabla F(\tilde{x}), z \rangle, \text{ where } \tilde{x} \text{ is a point on an interval connecting } x \text{ and } x+z$$

$$\Leftrightarrow F(x+z) - F(x) = \langle \nabla F(x), z \rangle + \langle \nabla F(\tilde{x}) - \nabla F(x), z \rangle$$

$$\begin{aligned} \text{Let } x_{t+1} &= x_t - h \nabla F(x_t) & F(x_{t+1}) - F(x_t) &= \langle \nabla F(x_t), -h \nabla F(x_t) \rangle \\ & & &+ \langle \nabla F(\tilde{x}) - \nabla F(x_t), -h \nabla F(x_t) \rangle \\ & & &= -h \|\nabla F(x_t)\|^2 + \|\nabla F(\tilde{x}) - \nabla F(x_t)\| \cdot h \|\nabla F(x_t)\| \\ & & &\leq -h \|\nabla F(x_t)\|^2 + L \|\tilde{x} - x_t\| \cdot h \|\nabla F(x_t)\| \\ & & &\leq -h \|\nabla F(x_t)\|^2 + L \|x_{t+1} - x_t\| \cdot h \|\nabla F(x_t)\| \\ & & & & \quad h \|\nabla F(x_t)\| \\ & & &\leq -h \|\nabla F(x_t)\|^2 + 2L^2 h^2 \|\nabla F(x_t)\|^2 \end{aligned}$$

If $h \in \frac{1}{2L}$, then RHS $\leq -\frac{h}{2} \|\nabla F(x_t)\|^2$

$$\sum_{t=0}^T F(x_{t+1}) - F(x_t) = F(x_{T+1}) - F(x_0) \leq -\frac{h}{2} \sum_{t=0}^T \|\nabla F(x_t)\|^2$$

$$\Rightarrow \nabla F(x_t) \rightarrow 0 \quad \Rightarrow x_t \xrightarrow{t \rightarrow \infty} x_* \quad \text{st. } \nabla F(x_*) = 0$$

$$W_{t+1} = W_t + h \sum_j x_j x_j$$

On the one hand,

$$\begin{aligned}
 F(W_{t+1}) &= F(W_t) + \langle \nabla F(W_t), W_{t+1} - W_t \rangle + \langle \nabla F(\tilde{W}) - \nabla F(W_t), W_{t+1} - W_t \rangle \\
 \tilde{W} &\in [W_t, W_{t+1}] \\
 \Rightarrow F(W_{t+1}) - F(W_t) &\leq h \underbrace{\langle \nabla F(W_t), \sum_j x_j x_j \rangle}_{\geq h^2} \\
 &\leq -h + h^2 \underbrace{\| \sum_j x_j x_j \|^2}_{\in M} \leq -h + h^2 M^2
 \end{aligned}$$

Take the sum for $t=0, \dots, T$

$$\begin{aligned}
 &F(W_{T+1}) - F(W_0) + F(W_1) - F(W_0) + \dots \\
 &= F(W_{T+1}) - F(W_0) \leq -hT + Th^2 M^2
 \end{aligned}$$

Since the number of steps at perception does not depend on h

We have that

$$\frac{1}{2} \|W_{T+1} - W_0\|^2 - \frac{1}{2} \|W_0\|^2 \leq -hT + Th^2 M^2$$

We know that $\|W_0\| \leq \frac{1}{8}$

$$hT \leq Th^2 M^2 + \frac{1}{2} \|W_0\|^2 - \frac{1}{2} \|W_{T+1} - W_0\|^2$$

$$\leq Th^2 M^2 + \frac{1}{2h} \|W_0\|^2 \quad \forall h > 0$$

Optimize over $h \Rightarrow \sqrt{T} \leq (\sqrt{2} + \frac{1}{\sqrt{2}}) \sqrt{T} \|W_0\| \cdot M^2$

$$T \leq (\sqrt{2} + \frac{1}{\sqrt{2}})^2 \|W_0\|^2 \cdot M^2 = (\sqrt{2} + \frac{1}{\sqrt{2}})^2 \left(\frac{M}{8}\right)^2$$

Logistic Regression (an example of a "generalized linear model")

It is an example of a discriminative model: namely, it specifies the form of $P(Y|X=x)$

Here, we will assume that $X \in \mathbb{R}^d$, $Y \in \{0, 1\}$

Assume that $P(Y=1|X=x) = p(x)$ - function of x

Remark if $p(x) > \frac{1}{2} \Rightarrow$ the best guess is $Y=1$, otherwise $Y=0$.

Note that (x_1, y_1) is the observed data, then $\mathcal{L}(p(x)) = p(x)^{y_1} (1-p(x))^{1-y_1}$

If the training data is $(x_1, y_1), \dots, (x_n, y_n)$

then $\mathcal{L}(p(x)) = \prod_{j=1}^n p(x_j)^{y_j} (1-p(x_j))^{1-y_j}$

$$p(x)^{y_j} = e^{y_j \log p(x)} \quad \Leftrightarrow \quad e^{\sum_{j=1}^n y_j \log p(x_j) + \sum_{j=1}^n (1-y_j) \log (1-p(x_j))}$$

$$\log \mathcal{L}(p(x)) = \underbrace{\sum_{j=1}^n y_j \log \frac{p(x_j)}{1-p(x_j)}}_{\text{"log odds ratio"}} + \sum_{j=1}^n \log (1-p(x_j))$$

Main assumption: $\log \frac{p(x)}{1-p(x)} = \langle w, x \rangle + b = \langle \tilde{w}, \tilde{x} \rangle$
 $\tilde{x} = (x, 1) \in \mathbb{R}^{d+1}$
 $\tilde{w} = (w, b) \in \mathbb{R}^{d+1}$

$$\log \mathcal{L} = \sum_{j=1}^n y_j \langle \tilde{w}_j, \tilde{x}_j \rangle + \sum_{j=1}^n \log (1-p(x_j))$$

$$\frac{p(x)}{1-p(x)} = e^{\langle \tilde{w}, \tilde{x} \rangle} = p(\tilde{x}) = \frac{e^{\langle \tilde{w}, \tilde{x} \rangle}}{1 + e^{\langle \tilde{w}, \tilde{x} \rangle}} \Rightarrow 1-p(\tilde{x}) = \frac{1}{1 + e^{\langle \tilde{w}, \tilde{x} \rangle}}$$

Therefore, maximizing $\log \mathcal{L}(p)$ is equivalent to maximizing

$$\sum_{j=1}^n y_j \langle \tilde{w}_j, \tilde{x}_j \rangle - \sum_{j=1}^n \log (1 + e^{\langle \tilde{w}_j, \tilde{x}_j \rangle})$$

$$\Leftrightarrow \sum_{j=1}^n \log (1 + e^{\langle \tilde{w}_j, \tilde{x}_j \rangle}) = \sum_{j=1}^n y_j \langle \tilde{w}_j, \tilde{x}_j \rangle \Rightarrow \text{convex}$$

minimize over $\tilde{w} \in \mathbb{R}^{d+1}$

\Rightarrow it has a unique minimizer \tilde{w}

Remark: a sufficient condition for F to be convex is that the eigenvalues of the Hessian have to be nonnegative

Let \hat{w} be the optimal solution $\Rightarrow \hat{p}(x) = \frac{e^{\langle \hat{w}, x \rangle}}{1 + e^{\langle \hat{w}, x \rangle}}$

$$p(x) \geq \frac{1}{2} \Leftrightarrow e^{\langle \hat{w}, x \rangle} \geq 1$$

$$\Leftrightarrow \langle \hat{w}, x \rangle \geq 0$$

Boosting

$$G = \{g : S \rightarrow \{+1, -1\}\}$$

Example will be on BB

Q: What if we look at classifiers of the form $\text{sign}(\alpha g_1 + (1-\alpha)g_2)$, $g_1, g_2 \in G$, $\alpha \in (0, 1)$

Recall that our goal is to find some g (a binary classifier) s.t. $\Pr(Y \neq g(x))$ is small

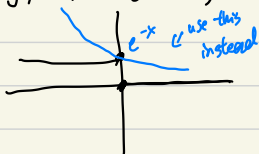
Note that $\Pr(Y \neq g(x)) = \Pr(Yg(x) < 0) = \mathbb{E} \mathbb{I}\{Yg(x) < 0\}$

Any function $f : S \rightarrow \mathbb{R}$ can be transformed into a binary classifier $g_f = \text{sign}(f) = \begin{cases} +1, & f \geq 0 \\ -1, & f < 0 \end{cases}$

Problem: given a class G of function $g : S \rightarrow \mathbb{R}$, minimize the empirical risk

$$\frac{1}{n} \sum_{j=1}^n \mathbb{I}\{y_j g(x_j) < 0\}$$

Indicator function



(1) $f(x) = e^{-x}$ is convex

$$f''(x) = e^{-x} > 0$$

(2) $e^{-x} \geq \mathbb{I}\{x \leq 0\}$

Instead, consider the problem $\frac{1}{n} \sum_{j=1}^n e^{-y_j g(x_j)} \rightarrow$ minimize over $g \in G$

The function $z \mapsto e^{-z}$ is convex, so this can often be done numerically.

Question Since $\forall g \in G$, $\frac{1}{n} \sum_{j=1}^n e^{-y_j g(x_j)} \geq \mathbb{E} e^{-Yg(x)}$

it's natural to ask which g minimizes $\mathbb{E} e^{-Yg(x)}$ over all $g : S \rightarrow \mathbb{R}$

Reminder: The minimum of $\mathbb{E} \mathbb{I}\{Y \neq g(x) < 0\}$ is achieved for $g(x) = \text{sign}(\mathbb{E}(Y|X=x))$

Theorem: Let \tilde{g} minimize $\mathbb{E} e^{-Yg(x)}$. Then $\text{sign}(\tilde{g}) = g^*$

Proof: Assume that X takes values x_1, \dots, x_k . (Discrete)

$$\mathbb{E} e^{-Yg(x)} = \sum_{j=1}^k \mathbb{E}[e^{-Yg(x)} | X=x_j] \Pr(X=x_j)$$

$$\mathbb{E}[e^{-Yg(x)} | X=x_k] = e^{-1 \cdot g(x_k)} P_r(Y=1 | X=x_k) + e^{-(-1) \cdot g(x_k)} P_r(Y=-1 | X=x_k)$$

We know that $P_r(Y=1 | X=x_k) = \frac{1 + \eta(x_k)}{2}$ $P_r(Y=-1 | X=x_k) = \frac{1 - \eta(x_k)}{2}$

where $\eta(x_k) = \mathbb{E}[Y | X=x_k]$ (let $\theta(x_k) = \frac{t}{2}$) $P_r(Y=t | X=x_k) = \frac{1 + t\eta(x_k)}{2}$ $t=1$ or -1

Therefore, it suffices to minimize $F(t) = e^{-t} \frac{1 + \eta(x_k)}{2} + e^t \frac{1 - \eta(x_k)}{2}$ over $t \in \mathbb{R}$

$F(t) > 0$, $F''(t) = F(t) > 0$, F is convex

$$F'(t) = -\frac{1}{2} \frac{1 + \eta(x_k)}{e^t} + e^t \frac{1 - \eta(x_k)}{2} = 0$$

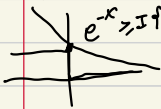
$$= -(1 + \eta(x_k)) + e^{2t} (1 - \eta(x_k)) = 0 \Rightarrow e^{2t} = \frac{1 + \eta(x_k)}{1 - \eta(x_k)}, t = \frac{1}{2} \log \frac{1 + \eta(x_k)}{1 - \eta(x_k)}$$

\mathcal{F} - "base class" of binary classifiers (e.g. threshold classifiers)

$$\mathcal{G} = \left\{ \sum_{j=1}^k \alpha_j f_j, k \geq 1, \alpha_1, \dots, \alpha_k \geq 0, f_1, \dots, f_k \in \mathcal{F} \right\}$$

Any $g \in \mathcal{G}$ can be transformed into a binary classifier via $g \rightarrow \text{sign}(g)$

Recall that for any binary classifier h , $\mathbb{I}\{Y \neq h(x)\} = \mathbb{I}\{Yh(x) < 0\}$



$\mathbb{E} \mathbb{I}\{Yg(x) < 0\}$ is minimized for $g(x) = \text{sign}(\mathbb{E}(Y|X=x))$

In the expression $\mathbb{E} e^{-Yg(x)}$ is minimized for $\tilde{g}(x) = \frac{1}{2} \log \frac{1 + \eta(x)}{1 - \eta(x)}$, where

$$\eta(x) = \mathbb{E}(Y|X=x)$$

$$\text{sign}\left(\frac{1 + \eta(x)}{1 - \eta(x)}\right) = 1 \Leftrightarrow \frac{1 + \eta(x)}{1 - \eta(x)} \geq 1 \Leftrightarrow \eta(x) \geq 0 = \text{sign}(\eta(x))$$

\Rightarrow we recover the Bayes classifier!

Summary: minimizing $\mathbb{E} e^{-Yg(x)}$ over all functions g gives us a Bayes classifier.

\Rightarrow it makes sense to look at the "empirical" version of this problem,

$$\frac{1}{n} \sum_{j=1}^n e^{-Y_j g(x_j)}$$

where $(x_1, y_1), \dots, (x_n, y_n)$ is the training data.

Let \mathcal{G} be a class of functions, and let us consider minimizing $\frac{1}{n} \sum_{j=1}^n e^{-Y_j g(x_j)}$ over $g \in \mathcal{G}$

Definition: We will say that a class F of binary classifier satisfies the following for any $n \geq 1$, any $(x_1, y_1), \dots, (x_n, y_n)$, any non-negative weights w_1, \dots, w_n s.t. $\sum_j w_j = 1$, $\exists f \in F$ s.t. $\sum_j w_j \mathbb{I}\{y_j \neq f(x_j)\} \leq \frac{1}{2}$
i.e. probability

Remark: If $f \in F \Leftrightarrow -f \in F \Rightarrow$ then F satisfies the weak learnability assumption.
 If loss $f > \frac{1}{2}$, we pick $-f$ which is $\leq \frac{1}{2}$ satisfied

$$\frac{1}{n} \sum_{j=1}^n e^{-y_j g(x_j)} \rightarrow \text{minimize over } g \in G$$

Using the notion of pseudogradient descent

Assume that, at iteration t , we have $g_t \in G$

$$\frac{1}{n} \sum_{j=1}^n e^{-y_j (g_t(x_j) + \alpha f(x_j))}$$

Goal: find $\alpha \in \mathbb{R}$, $f \in F$ that make this expression as small as possible

The function f can be viewed as a "proxy" to the gradient.

The methods of this type are referred to as "steepest descent" methods. non ok.

$$\rightarrow = \frac{1}{n} \sum_{j=1}^n e^{-y_j g(x_j)} e^{-y_j \alpha f(x_j)}$$

$$\text{Let } w_j = \frac{1}{n} e^{-y_j g(x_j)} > 0$$

Then, we are trying to minimize $\sum_{j=1}^n w_j e^{-\alpha y_j f(x_j)}$ over $f \in F, \alpha \in \mathbb{R}$

If $\tilde{w}_j = \frac{w_j}{\sum_j w_j}$ so that $\sum_j \tilde{w}_j = 1$, then we need to minimize $\sum_j \tilde{w}_j e^{-\alpha y_j f(x_j)}$

$$\text{Note that } \sum_j \tilde{w}_j e^{-\alpha y_j f(x_j)} = \sum_j \tilde{w}_j e^{-\alpha} \mathbb{I}\{y_j = f(x_j)\} + \sum_j \tilde{w}_j e^{\alpha} \mathbb{I}\{y_j \neq f(x_j)\} \\ \pm \sum_j \tilde{w}_j e^{-\alpha} \mathbb{I}\{y_j \neq f(x_j)\} = e^{-\alpha} \sum_j \tilde{w}_j + (e^{\alpha} - e^{-\alpha}) \sum_j \tilde{w}_j \mathbb{I}\{y_j \neq f(x_j)\}$$

$$= e^{-\alpha} + (e^{\alpha} - e^{-\alpha}) \sum_j \tilde{w}_j \mathbb{I}\{y_j \neq f(x_j)\}$$

To minimize this expression, (1) minimize $\sum_j \tilde{w}_j \mathbb{I}\{y_j \neq f(x_j)\}$ WRT $f \in F$

(2) minimize wrt α

$$\text{Let } e_{n,\alpha}(f) = \sum_j \tilde{w}_j \mathbb{I}\{y_j \neq f(x_j)\}$$

$$\text{Weak Learnability} \Rightarrow \exists \{ \tilde{w}_j \}_{j=1}^n, \exists f \in F \text{ s.t. } e_{n,\alpha}(f) \leq \frac{1}{2}$$

Next, the minimum $\alpha \rightarrow e^{-\alpha} + (e^{\alpha} - e^{-\alpha}) e_{n,\alpha}(f)$ is achieved

$$\hat{\alpha} = \frac{1}{2} \log \frac{1 - e_{n,\hat{\alpha}}(f)}{e_{n,\hat{\alpha}}(f)}$$

Adaboost

Initialize $w_j^{(1)} = \frac{1}{n}$, $j=1, \dots, n$, $g_0 = 0$ for $t=1, \dots, T$ do

(i) Call the weak Learner

(ii) WL outputs f_t s.t. $e_{n,w_t}(f_t) \leq \frac{1}{2}$

(iii) $\alpha_t = \frac{1}{2} \log \frac{1 - e_{n,w_t}(f_t)}{e_{n,w_t}(f_t)} \geq 0$

(iv) Update the weights

$$w_j^{(t+1)} = \frac{w_j^{(t)} e^{-\gamma \alpha_t f_t(x_j)}}{Z_t} \quad \text{normalizing factor}$$

$$Z_t = \sum_j^n w_j^{(t)} e^{-\gamma \alpha_t f_t(x_j)}$$

$$\text{Output } \hat{g}_T = \frac{\sum_{t=1}^T \alpha_t f_t}{\sum_{t=1}^T \alpha_t}$$

Theorem Assume that for any probability w_1, \dots, w_n , the WL finds f s.t. $\sum_j w_j \mathbb{I}\{f_j \neq f(x_j)\} \leq \frac{1}{2} - \gamma$ for some $\gamma > 0$. Then the training error of Adaboost satisfies $\frac{1}{n} \sum_j^n \mathbb{I}\{f_j \neq \text{sign}(\hat{g}_T(x_j))\} \leq e^{-2T\gamma^2}$

$$\text{Proof: } \frac{1}{n} \sum_j^n \mathbb{I}\{f_j \neq \text{sign}(\hat{g}_T(x_j))\} = \frac{1}{n} \sum_j^n \mathbb{I}\{f_j \hat{g}_T(x_j) < 0\} \leq \frac{1}{n} \sum_j^n e^{-\gamma \hat{g}_T(x_j)} = \frac{1}{n} \sum_j^n e^{-\gamma \sum_{t=1}^T \alpha_t f_t(x_j)}$$

$$\text{Note that } w_j^{(t+1)} = \frac{1}{n} \frac{e^{-\gamma \sum_{i=1}^t \alpha_i f_i(x_j)}}{\sum_j \frac{1}{n} e^{-\gamma \sum_{i=1}^t \alpha_i f_i(x_j)}}$$

$$e^{-\gamma \sum_{i=1}^t \alpha_i f_i(x_j)} = n \sum_j \frac{1}{n} e^{-\gamma \sum_{i=1}^t \alpha_i f_i(x_j)} w_j^{(t+1)}$$

$$Z_t = \sum_j^n w_j^{(t)} e^{-\alpha_t \gamma f_t(x_j)}$$

$$= e^{-\alpha_t \gamma} + (e^{\alpha_t \gamma} - e^{-\alpha_t \gamma}) \sum_j^n w_j^{(t)} \mathbb{I}\{f_j \neq f_t(x_j)\}$$

$$\text{Plug in } \alpha_t = \frac{1}{2} \log \frac{1 - e_{n,w_t}(f_t)}{e_{n,w_t}(f_t)}$$

$$e_{n,w_t}(f_t) = \sum_j^n w_j^{(t)} \mathbb{I}\{f_j \neq f_t(x_j)\}$$

$$Z_t = 2 \sqrt{e_{n,w_t}(f_t) (1 - e_{n,w_t}(f_t))} \leq 2 \sqrt{\left(\frac{1}{2} - \gamma\right) \left(\frac{1}{2} + \gamma\right)}$$

Regression and Linear Regression

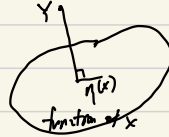
Assume that Y can take values beyond $\{-1, +1\}$ (or $\{0, 1\}$), specifically assume that $Y \in \mathbb{R}$

- Y will be called the "response variable".
- The goal is to predict Y based on the observation X
 - $x \in \mathbb{R}^d$, the coordinates of x are called "features".
 - X is also called the "predictor variable".

Example Predict the final exam grade = Y base on (midterm grade, hw1, hw2)
 predictor
 features

Reminder: The condition expectation of Y given $X=x$, denoted $\eta(x)$, minimize $\mathbb{E}_{Y|X=x}(Y-x)^2$

In other words, $\eta(x) = \mathbb{E}(Y|X=x)$ is the best functional approximation of Y as a function of X



Mathematically,

$\eta(x)$ minimizes $\mathbb{E}(Y - f(x))^2$ over all functions f .

Given the training data $(X_1, Y_1), \dots, (X_n, Y_n)$, we consider the problem of minimizing $\frac{1}{n} \sum_{j=1}^n (Y_j - f(X_j))^2$ over $f \in F$

Question: Let \hat{f}_n be the solution of the problem. What is $\mathbb{E}(Y - \hat{f}_n(x))^2$?

Note that $\mathbb{E}(Y - \hat{f}_n(x))^2 = \mathbb{E}(Y - \eta(x) + \eta(x) - \hat{f}_n(x))^2$
 orthogonal

$$\begin{aligned} &= \mathbb{E}(Y - \eta(x))^2 + \mathbb{E}(\eta(x) - \hat{f}_n(x))^2 + 2 \underbrace{\mathbb{E}(Y - \eta(x))(\eta(x) - \hat{f}_n(x))}_0 \\ &= \mathbb{E}(Y - \eta(x))^2 + \mathbb{E}(\eta(x) - \hat{f}_n(x))^2 \\ &< \mathbb{E}(Y - \eta(x))^2 + \mathbb{E}(\eta(x) - \hat{f}_n(x))^2 \leftarrow \text{approximation error} \right. \\ &\quad \left. + \mathbb{E}(\hat{f}_n(x) - \hat{f}_n(x))^2 \leftarrow \text{training error} \right. \mathbb{E} \left[\mathbb{E}[(Y - \eta(x))(\eta(x) - \hat{f}_n(x)) | X] \right] \\ &\quad \mathbb{E}(Y | X) = \eta(x) \end{aligned}$$

Comparison to Multivariate statistical

$$Y = \alpha X + \beta + \varepsilon, \quad \varepsilon \sim N(0, \sigma^2)$$

MLE of (α, β) is given by the solution of
 $\frac{1}{n} \sum_{j=1}^n (Y_j - \alpha' X_j - \beta)^2 \rightarrow$ minimize over α', β' .

Fact: If (Y, X) has bivariate normal distribution then,
 $E(Y|X=x) = \alpha X + b!$

app error

$$E(\eta(x) - \hat{f}(x)) = 0$$

Error decomposition in linear regression

$$E(Y - g(x))^2 = E(Y - \eta(x))^2 + \underbrace{E(\bar{g}(x) - \eta(x))^2}_{\text{app error of } G} + E(g(x) - \bar{g}(x))^2$$

In statistics, a common assumption is that (X, Y) has multivariate normal distribution. In this case, $\eta(x) = \langle w_*, x \rangle + b_*$ is a linear function of x , and $\frac{Y - \eta(x)}{\sigma}$ is normally distributed. $Y = \langle w_*, x \rangle + b_* + \varepsilon$

• Allows to do inference: build confidence intervals / test statistic hypothesis.

Solution of linear regression problem

$$G = \langle g_{w,b}(x) = \langle w, x \rangle + b \rangle$$

Goal: find \hat{w}, \hat{b} that minimize

$$\frac{1}{n} \sum_{j=1}^n (Y_j - \langle w, x_j \rangle - b)^2 \text{ over } w \in \mathbb{R}^d, b \in \mathbb{R}$$

Simplify: $\tilde{X}_j = (X_j, 1) \in \mathbb{R}^{d+1}$
 $\tilde{w} = (w, b) \in \mathbb{R}^{d+1}$

$$\langle \tilde{w}, \tilde{X}_j \rangle = \langle w, x_j \rangle + b$$

$$\text{Let } \tilde{Y} = \begin{pmatrix} Y_1 \\ \vdots \\ Y_n \end{pmatrix} \quad X = \begin{pmatrix} \tilde{X}_1 \\ \vdots \\ \tilde{X}_n \end{pmatrix}$$

$$\begin{pmatrix} Y_1 - \langle \tilde{X}_1, \tilde{w} \rangle \\ Y_2 - \langle \tilde{X}_2, \tilde{w} \rangle \\ \vdots \\ Y_n - \langle \tilde{X}_n, \tilde{w} \rangle \end{pmatrix} = \tilde{Y} - X \tilde{w}$$

Then $\frac{1}{n} \sum (y_j - \langle \tilde{w}, \tilde{x}_j \rangle)^2 = \frac{1}{n} \| \tilde{Y} - X \tilde{w} \|_2^2 = F(w)$
 If $X = (x^{(1)} | x^{(2)} | \dots | x^{(d+1)})$

$H(w) = X w$, $\nabla H(w) = X$
 $\nabla F(w) = -2 X^T (Y - X \tilde{w}) = 0$
 $(X^T X) \tilde{w} = X^T Y$ (normal equations)
 If $(X^T X)$ is invertible
 $X \in \mathbb{R}^{n \times (d+1)}$, $n > d+1$
 $X^T X \in \mathbb{R}^{(d+1) \times (d+1)}$

$\therefore \hat{w} = (X^T X)^{-1} X^T Y$

Continue:

$\hat{w} = (X^T X)^{-1} X^T Y$ if $X^T X$ is invertible.

$\Leftrightarrow \underbrace{(X^T X)}_A \hat{w} = \underbrace{X^T Y}_b$

$A \hat{w} = b$

$X^T X = (X^T X)^T \Rightarrow X^T X = V \Lambda_x V^T$ where $V = (v_1 | \dots | v_p)$ is a matrix of orthonormal vectors.
 $\Lambda_x = \begin{pmatrix} \lambda_1 & & 0 \\ & \dots & \\ 0 & & \lambda_p \end{pmatrix}$, $\lambda_1, \dots, \lambda_p$ - eigenvalues.

$V \Lambda_x V^T \hat{w} = X^T Y$ Since $V^T V = I_p$, $\Lambda_x V^T \hat{w} = V^T X^T Y$ $V^T \hat{w} = \Lambda_x^{-1} (X^T Y)$

The Ridge Regression

Let $\lambda > 0$ - the "regularization parameter"

$\frac{1}{n} \| \tilde{Y} - X w \|_2^2 + \lambda \| w \|_2^2 \rightarrow$ minimize over $w \in \mathbb{R}^{d+1}$

regularization / penalty term
 Tikhonov regularization

$F(w) = \frac{1}{n} \| \tilde{Y} - X w \|_2^2 + \lambda \| w \|_2^2$

$\nabla F(w) = -\frac{2}{n} X^T (Y - X w) + 2 \lambda w$

$\nabla F(w) = 0 \Leftrightarrow \frac{2}{n} X^T Y - 2(X^T X)w + 2\lambda w$

\hat{w} solves the system

$$X^T X w + \lambda I \cdot w = X^T Y \Leftrightarrow (X^T X + \lambda I) w = X^T Y$$

$$\hat{w} = (X^T X + \lambda I)^{-1} X^T Y$$

$$\text{If } X^T X = V \Lambda V^T, \text{ then } X^T X + \lambda I = V(\Lambda + \lambda I) V^T$$

Numerical Instability problem disappears, but need to pay attention to $\lambda/\|w\|_2^2$.

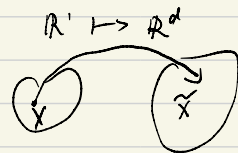
Polynomial Regression (linear regression for polynomial functions).

Assume that $(X, Y) \in \mathbb{R} \times \mathbb{R}$

$$G = \{ p(x) = a_0 + a_1 x + \dots + a_d x^d, a_0 \dots a_d \in \mathbb{R} \}$$

Idea: create a mapping $X \mapsto (x, x^2, x^3, \dots, x^d)$

feature space



$$(X_1, Y_1), \dots, (X_n, Y_n) \mapsto (\tilde{X}_1, Y_1), \dots, (\tilde{X}_n, Y_n)$$

$$\langle w, \tilde{x} \rangle = w_0 x + w_1 x^2 + \dots + w_d x^d$$

Linear regression problem corresponds to solving $\frac{1}{n} \sum_{i=1}^n (Y_i - \sum_{j=0}^d w_j x_i^j)^2$

Also the idea of SVM

Non-learnability of Linear Regression

Let $(X, Y) \in \mathbb{R} \times \mathbb{R}$, and $G = \{ f_w(x) = wx, w \in \mathbb{R} \}$

What does it mean for G to be "learnable"?

It means that \exists an algorithm A , s.t. for any distribution over (X, Y) , and $\epsilon, \delta > 0$,

$\exists n = n(\epsilon, \delta)$, such that for all $n \geq n(\epsilon, \delta)$, $A((X_1, Y_1), \dots, (X_n, Y_n))$ outputs \hat{w} , s.t.

$$\mathbb{E} (Y - \hat{w}_n X)^2 \leq \min_{w \in \mathbb{R}} \mathbb{E} (Y - wX)^2 + \epsilon \text{ with probability } \geq 1 - \delta.$$

Example let $\epsilon = 0.01$, $\delta = 0.5$, $n \geq n(\epsilon, \delta)$

let $\mu = \frac{\log(\frac{100}{\delta})}{2n}$. Consider two distributions.

$$P_1: \begin{array}{c} Y=1 \\ \mu \\ \hline Y=0 \\ 1 \end{array} \rightarrow$$

$$P_1((X, Y) = (1, 0)) = \mu$$

$$P_1((X, Y) = (\mu, -1)) = 1 - \mu$$

$$P_2: \begin{array}{c} Y=-1 \\ \mu \\ \hline 1 \end{array} \rightarrow$$

$$P_2((X, Y) = (\mu, -1)) = 1$$

P_1

P_2

For P_1 , $\Pr(x_1 = \dots = x_n = \mu) = (1-\mu)^n \geq e^{-2\mu n} = 0.99$

Since $1-\mu \geq e^{-2\mu} = 1-2\mu + \frac{(2\mu)^2}{2} = 1-2\mu + 2\mu^2$

$1-\mu \geq 1-2\mu + 2\mu^2$ when $\mu \geq 0$

For P_2 , $\Pr(x_1 = \dots = x_n = \mu) = 1$

We don't know whether the observation comes from which distro
 $\Rightarrow A$ will produce the same output \hat{w}_n regardless of the distribution.

(i) $|\hat{w}_n| < \frac{1}{2\mu}$, then $\mathbb{E}_{P_1}(Y - \hat{w}_n X)^2 = \mathbb{E}(1 - \hat{w}_n \mu)^2$ $|\hat{w}_n \mu| < \frac{1}{2}$
 $\geq (1 - \frac{1}{2})^2 = \frac{1}{4}$

But $\min_w \mathbb{E}(Y - wX)^2 = 0$, for $w = -\frac{1}{\mu}$

(ii) $|\hat{w}_n| \geq \frac{1}{2\mu}$ Consider P_2 : $\mathbb{E}_{P_2}(Y - \hat{w}_n X)^2 = \mu(0 - \hat{w}_n \cdot 1)^2 + (1-\mu)(1 - \hat{w}_n \mu)^2$
 $\geq \mu \cdot \mu^2 \geq \frac{1}{4\mu}$
 $\mu = \frac{(1-\mu)^2}{2n}$

But $\min_w \mathbb{E}_{P_2}(Y - wX)^2 \leq \mathbb{E}_{P_2}(Y - 0 \cdot X)^2 = 1 - \mu$

$\frac{1}{4\mu} - (1-\mu) > \frac{1}{4\mu} - (1-\mu) > \epsilon = 0.01$ for n large enough

Remark: (a) To make the problem learnable, we need to assume that

(i) $\|x_k\|_2 \leq M$ (textbook details)

(ii) $\|w_k\|_2 \leq R$

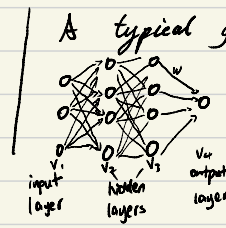
(b) Compare this to Gaussian linear regression:

$Y = \alpha X + \epsilon$, X, ϵ are independent, normally distributed, the no assumption on α is required.

Artificial Neural Nets

• Feedforward neural networks

(V, E) - a graph
 a set of vertices or nodes → edges



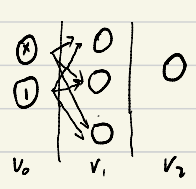
$V = \bigcup_{t=0}^T V_t$
 T - the depth of a network

Each edge in E connects a vertex in V_t to a vertex in V_{t+1} for some t .
 Nodes correspond to "artificial neurons".

Each neuron is modeled by an "activation function" $\sigma: \mathbb{R} \rightarrow \mathbb{R}$, such as

- (a) $\sigma(x) = \mathbb{I}\{x \geq 0\}$
- (b) $\sigma(x) = \frac{1}{1 + e^{-x}}$ (sigmoid)
- (c) $\sigma(x) = \max(0, x)$ (ReLU, rectified linear units).

Let $O_{t,i}(x)$ be the output of neuron i in level t when given input $x \in \mathbb{R}^d$.
 By design, $O_{0,j}(x) = x_j$, $O_{0,n+1}(x) = 1$. The input to $V_{t+1,j}$ (j -th neuron in layer $t+1$)



$$a_{t+1,j} = \sum W^{(t,r),(t+1,j)} O_{t,r}(x)$$

$r \in \{r, v_{t+1,j}\} \in E$

$$O_{0,1}(x) = x$$

$$O_{0,2}(x) = 1$$

$$a_{1,1} = W^{(0,1),(1,1)} \cdot x + W^{(0,2),(1,1)} \cdot 1$$

$$a_{1,2} = W^{(0,1),(1,2)} \cdot x + W^{(0,2),(1,2)} \cdot 1$$

$$a_{1,3} = W^{(0,1),(1,3)} \cdot x + W^{(0,2),(1,3)} \cdot 1$$

Apply activation function: $O_{1,1} = \sigma(a_{1,1})$, $O_{1,2} = \sigma(a_{1,2})$, $O_{1,3} = \sigma(a_{1,3})$

$$a_{2,1} = W^{(1,1),(2,1)} \cdot O_{1,1} + W^{(1,2),(2,1)} \cdot O_{1,2} + W^{(1,3),(2,1)} \cdot O_{1,3}$$

Explicitly: $a_{2,1} = W^{(1,1),(2,1)} \sigma(W^{(0,1),(1,1)} \cdot x + W^{(0,2),(1,1)} \cdot 1)$
 $+ W^{(1,2),(2,1)} \sigma(W^{(0,1),(1,2)} \cdot x + W^{(0,2),(1,2)} \cdot 1)$
 $+ W^{(1,3),(2,1)} \sigma(W^{(0,1),(1,3)} \cdot x + W^{(0,2),(1,3)} \cdot 1)$

$G_{V,E,\sigma} = \{ g_{V,E,\sigma,W}, W: E \rightarrow \mathbb{R} \}$ Graph representation

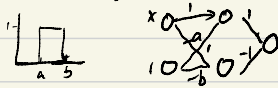
Question: how expensive can these classes be?

Th: Let $f: [0,1] \rightarrow \mathbb{R}$ that is continuous

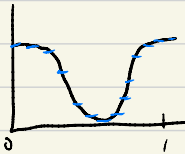
Then $\forall \epsilon > 0, \exists (V,E)$ and weights $w \in \mathbb{R}^{|E|}$, such that $|g_{V,E,w}(x) - f(x)| \leq \epsilon, \forall x \in [0,1]$.

We will take $\sigma(x) = \mathbb{I}\{x \geq 0\}$.

$$\mathbb{I}\{x \in (a,b)\} = \sigma(x-a) - \sigma(x-b)$$

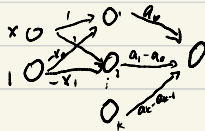


$\forall \epsilon > 0, \exists k$ and $0 < x_0 < \dots < x_k < 1$ s.t. $\forall j \leq k, |f(x) - f(\frac{x_{j-1} + x_j}{2})| \leq \epsilon$ for $x \in [x_{j-1}, x_j]$




$$\tilde{f}(x) = \sum_{j=1}^k a_j \mathbb{I}\{x \in [x_{j-1}, x_j)\} \text{ . Here, } a_j = f\left(\frac{x_{j-1} + x_j}{2}\right)$$

$$\begin{aligned} \text{Therefore, } \tilde{f}(x) &= \sum_{j=1}^k a_j (\sigma(x-x_{j-1}) - \sigma(x-x_j)) \\ &= \sum_{j=1}^k a_j \sigma(x-x_{j-1}) - \sum_{j=1}^k a_j \sigma(x-x_j) \\ &= a_0 \sigma(x-x_0) + \sum_{j=1}^{k-1} (a_{j+1} - a_j) \sigma(x-x_j) - a_k \sigma(x-x_k) \end{aligned}$$



1 hidden layer nn can approximate and continuous function.

final: given , approximate f with nn

Gradient Descent of NN

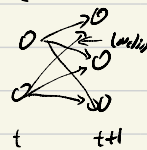
$$G = \{g_{V,E}, G, W, W \in \mathbb{R}^{|E|}\}$$

Goal: $\min F(W) = \frac{1}{2} \sum_{j=1}^n (Y_j - g_w(X_j))^2$ over $W \in \mathbb{R}^{|E|}$

$(V, E), V = \bigcup_{t=0}^T V_t, V_t = (v_{t,1}, \dots, v_{t,k_t}), W_t \in \mathbb{R}^{k_{t-1} \times k_t}$

$(W_t)_{i,j}$ = height on the edge b/w $v_{t+1,i}$ and $v_{t,j}$

$W = (W_0, \dots, W_{T-1}), F(W) = \frac{1}{2} \sum_{j=1}^n (Y_j - g_w(X_j))^2$



Pick some $t, i \leq k_{t+1}, j \leq k_t$

$\frac{\partial}{\partial (W_t)_{i,j}} F(W) = \frac{\partial}{\partial (W_t)_{i,j}} (g_w(X_j) - Y_j) \frac{\partial}{\partial (W_t)_{i,j}} g_w(X_j)$

Ex. $W, T=1 \Rightarrow$ no hidden layers

$g_w(x) = \sigma(W_0 \cdot x) = \sigma(W_0 \cdot O_0)$
 $\frac{\partial}{\partial (W_0)_i} g_w(x) = \sigma'(W_0 \cdot O_0) (O_0)_i$
 $\nabla_w g_w(x) = \sigma'(W_0 \cdot O_0) O_0$

Ex 2: 1 hidden layer

O_0 - output of layer 0
 $a_1 = W_0 O_0$ - inputs of layer 1

$$\left. \begin{array}{l} O_1 = \sigma(W_0 O_0) = \sigma(a_1) = \begin{pmatrix} \sigma(\langle W_{0,1}, O_0 \rangle) \\ \vdots \\ \sigma(\langle W_{0,k_1}, O_0 \rangle) \end{pmatrix} \\ a_2 = W_1 O_1 \\ O_2 = \sigma(a_2) = \sigma(W_1 O_1) = \sigma(W_1 \sigma(W_0 O_0)) \end{array} \right\}$$

$\nabla g_{W_1} = \sigma'(W_1 \sigma(W_0 O_0)) \cdot O_1$

Differentiate w.r.t. $W_0 \nabla g_{W_0} = \sigma'(W_1 \sigma(W_0 \vec{w}_0)) W_1 \sigma'(O_0 \vec{w}_0) O_0$, where $\sigma'(O_0 \vec{w}_0) = \begin{pmatrix} \sigma'(\langle W_{0,1}, O_0 \rangle) \\ \vdots \\ \sigma'(\langle W_{0,k_1}, O_0 \rangle) \end{pmatrix}$

Remark $W_t \in \mathbb{R}^{k_t \times k_{t-1}}, k_t = \#$ of nodes in layer t

$\begin{pmatrix} 1 \\ \vdots \\ k_t \end{pmatrix} \rightarrow (1 \ 2 \ \dots \ k_t)$

$O_{t-1} \in \mathbb{R}^{k_{t-1}} \rightarrow \begin{pmatrix} O_1^T & 0 & & 0 & 0 \\ 0 & O_2^T & & 0 & 0 \\ \vdots & & \ddots & & 0 \\ 0 & & & 0 & O_{t-1}^T \end{pmatrix} = O_{t-1}$

Then $W_t O_{t-1} = O_t$ W_t

$$\begin{aligned} \text{In general, } \nabla_{w_0} \sigma(w_{T-1} \sigma(w_{T-2} (\dots \sigma(w_0 o_0) \dots))) \\ = \sigma'(w_{T-1} o_{T-1}) w_{T-1} \sigma'(w_{T-2} o_{T-2}) \times \dots \times w_1 \sigma'(w_0 o_0) o_0 \end{aligned}$$